

자연대류를 포함한 열전달 해석 솔버 개선

buoyantSimpleFoam

길재흥

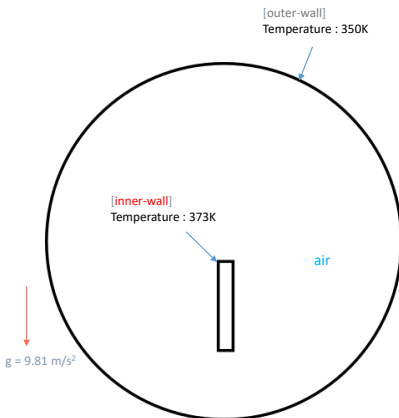
넥스트폼 기술연구소



문제 제기

간단한 예제

- Natural Convection in Closed Domain

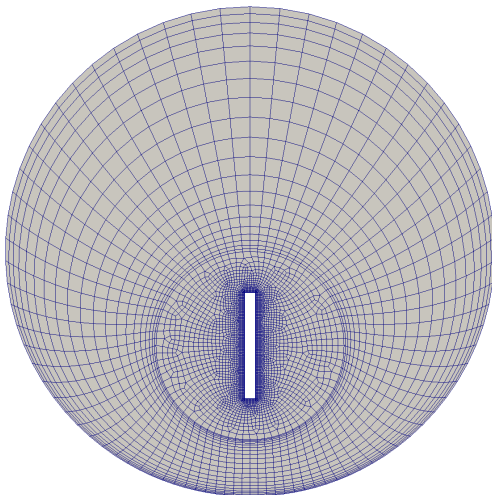


[air properties]

- density : perfect gas
- specific heat : constant
- viscosity : Sutherland's law
- conductivity : kinetic theory

간단한 예제

- Grid



buoyantSimpleFoam in OpenFOAM-4.0(2.4)

- Pressure Boundary Conditions : p
 - thermophysical properties를 update하기 위한 pressure

0/p

```
:\n\ninternalField      uniform 101325;\n\nboundaryField\n{\n    outer-wall\n    {\n        type        calculated;\n        value        $internalField;\n    }\n\n    inner-wall\n    {\n        type        calculated;\n        value        $internalField;\n    }\n\n    :\n    :\n}
```

buoyantSimpleFoam in OpenFOAM-4.0(2.4)

- Pressure Boundary Conditions : $p_{rgh} = p - \rho(\vec{g} \cdot \vec{r})$
 - 실제 계산에 사용되는 pressure(working pressure)

```
0/p_rgh
```

```
:\n:\n\ninternalField      uniform 101325;\n\nboundaryField\n{\n    outer-wall\n    {\n        type        fixedFluxPressure;\n        value        $internalField;\n    }\n\n    inner-wall\n    {\n        type        fixedFluxPressure;\n        value        $internalField;\n    }\n\n    :\n    :\n    :\n}
```

buoyantSimpleFoam in OpenFOAM-4.0(2.4)

- Momentum Equation

$$\nabla \cdot (\rho \vec{U} \vec{U}) = \nabla \cdot \bar{\bar{\tau}} - \nabla p - \rho \vec{g}$$

$$\nabla \cdot (\rho \vec{U} \vec{U}) = \nabla \cdot \bar{\bar{\tau}} - \nabla p_{rgh} - (\vec{g} \cdot \vec{r}) \nabla \rho$$

\vec{g} : *gravity vector*

$\bar{\bar{\tau}}$: *shear stress tensor*

$$\bar{\bar{\tau}} = \mu_{eff} \left\{ \nabla \vec{U} + (\nabla \vec{U})^T - \frac{2}{3} (\nabla \cdot \vec{U}) \bar{I} \right\}$$

$\mu_{eff} = \mu + \mu_t$: *effective dynamic viscosity*

$$p_{rgh} = p - \rho(\vec{g} \cdot \vec{r})$$

buoyantSimpleFoam in OpenFOAM-4.0(2.4)

- Pressure-Velocity Coupling
 - Use pseudo-velocity(\vec{U}_p^*) to derive pressure equation

$$\vec{U}_p^* = \frac{H(\vec{U}^*)}{a_p} - \frac{V_p}{a_p} \{(\vec{g} \cdot \vec{r}) \nabla \rho\}_p$$

$$\vec{U}_p = \vec{U}_p^* - \frac{V_p}{a_p} (\nabla p_{rgh})_p \quad (1)$$

$$\dot{m}_f = \rho_f \left\{ \frac{H(\vec{U}^*)}{a} \right\}_f \cdot \vec{S}_f - \underbrace{\rho_f \left(\frac{V}{a} \right)_f (\vec{g} \cdot \vec{r})_f \left(\frac{\partial \rho}{\partial n} \right)_f |\vec{S}_f|}_{\phi_g} - \rho_f \left(\frac{V}{a} \right)_f \left(\frac{\partial p_{rgh}}{\partial n} \right)_f |\vec{S}_f| \quad (2)$$

- Substituting equation (2) into discretized continuity equation($\sum \dot{m}_f = 0$) yields pressure equation

buoyantSimpleFoam in OpenFOAM-4.0(2.4)

- fixedFluxPressure
 - ϕ_g 에 대한 flux correction

pEqn.H

```

:
:
volScalarField rAU("rAU", 1.0/UEqn().A());
surfaceScalarField rhorAUf("rhorAUf", fvc::interpolate(rho*rAU));

volVectorField HbyA("HbyA", U);
HbyA = rAU*UEqn().H();
UEqn.clear();

surfaceScalarField phig(-rhorAUf*ghf*fvc::snGrad(rho)*mesh.magSf());

surfaceScalarField phiHbyA
(
    "phiHbyA",
    (fvc::interpolate(rho*HbyA) & mesh.Sf())
);

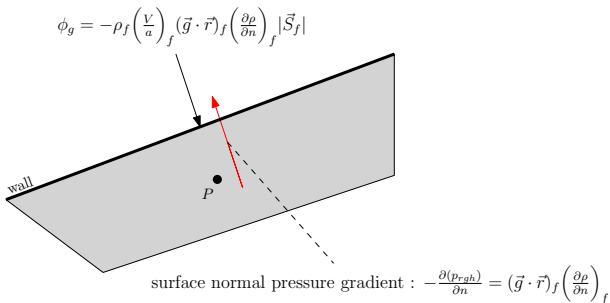
fvOptions.makeRelative(fvc::interpolate(rho), phiHbyA);
bool closedVolume = adjustPhi(phiHbyA, U, p_rgh);
phiHbyA += phig;

:
:

```

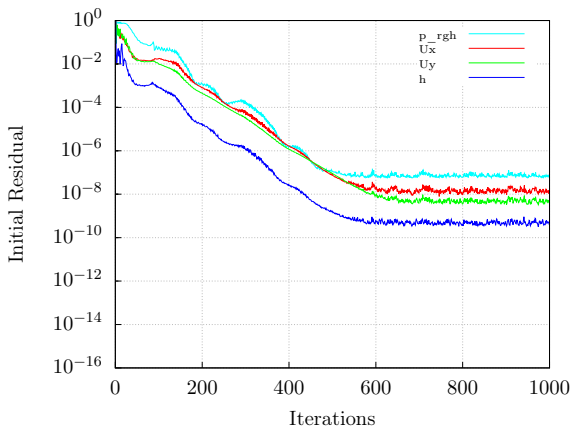
buoyantSimpleFoam in OpenFOAM-4.0(2.4)

- fixedFluxPressure
 - pressure laplacian 이산화과정에서 surface normal gradient가 ϕ_g 를 상쇄하도록



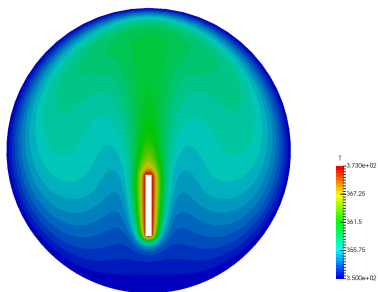
해석 결과

- 수렴성

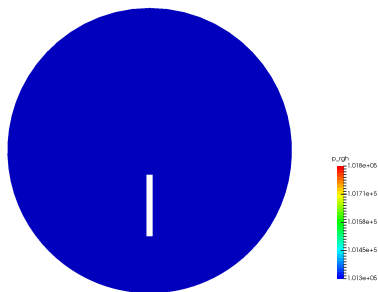


해석 결과

- 온도 및 압력



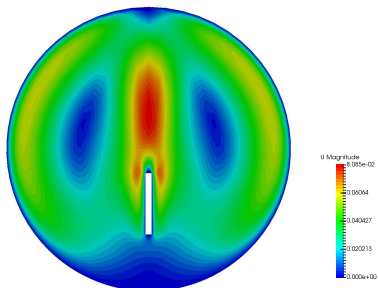
(a) 온도 분포



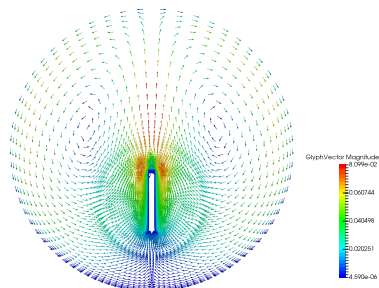
(b) 압력 분포(p_rgh)

해석 결과

- 속도



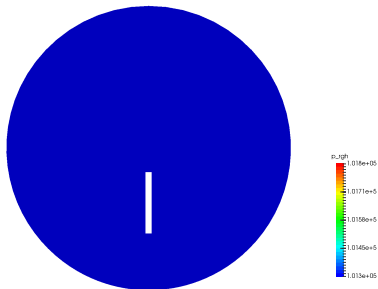
(a) 속도 분포



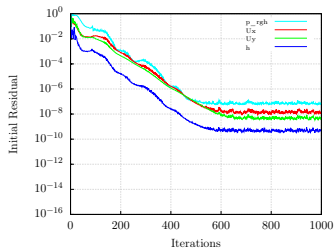
(b) 속도 벡터

문제점

- 압력 분포를 확인할 수 없음
- 수렴성(?)



(a) 압력 분포



(b) 수렴성

Operating Pressure

Operating Pressure

- 압력변화가 매우 작은 유동
 - Δp 계산시 round-off error 누적
 - 일정 수준의 압력(operating pressure)에 대한 상대압력을 이용하면 round-off error를 줄일수 있다.

$$p_{rgh} = p - \rho(\vec{g} \cdot \vec{r}) - p^{op}$$

pEqn.H

```

:
:
:
// Correct the momentum source with the pressure gradient flux
// calculated from the relaxed pressure
U = HbyA + rAU*fvc::reconstruct((phig - p_rghEqn.flux())/rhoxAUf);
U.correctBoundaryConditions();
fvOptions.correct(U);
}
}

#include "continuityErrs.H"

p = p_rgh + rho*gh + Op;

:
:

```


Operating Pressure

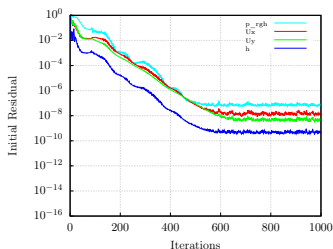
- Specifying Operating Pressure

createFields.H

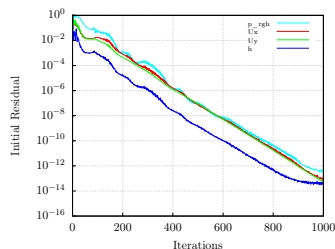
```
:  
:  
:  
IOdictionary operatingConditions  
(  
    IOobject  
    (  
        "operatingConditions",  
        runTime.constant(),  
        mesh,  
        IOobject::MUST_READ_IF_MODIFIED,  
        IOobject::NO_WRITE  
    )  
);  
dimensionedScalar Op(operatingConditions.lookup("Op"));  
  
:  
:  
:
```

Operating Pressure

- 수렴성



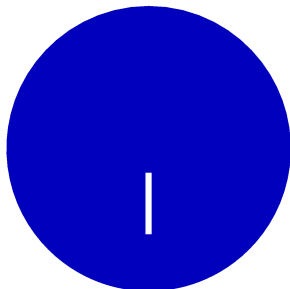
(a) $p^{op} = 0$



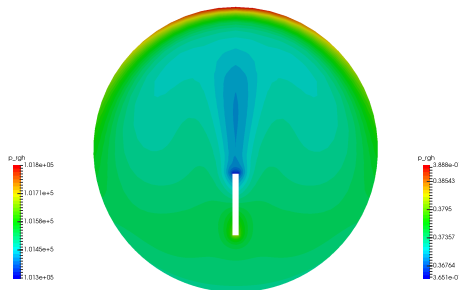
(b) $p^{op} = 101325$

Operating Pressure

- 압력(p_{rgh})



(a) $p^{op} = 0$



(b) $p^{op} = 101325$

Operating Density

Re-define Working Pressure(p_{rgh})

- OpenFOAM

$$p_{rgh} = p - \rho(\vec{g} \cdot \vec{r})$$

- Commercial Codes

$$p_{rgh} = p - \rho_0(\vec{g} \cdot \vec{r})$$

ρ_0 : average density or specified as constant

Re-define Working Pressure(p_{rgh})

- Resulting Momentum Equation
 - OpenFOAM

$$\nabla \cdot (\rho \vec{U} \vec{U}) = \nabla \cdot \bar{\bar{\tau}} - \nabla p_{rgh} - (\vec{g} \cdot \vec{r}) \nabla \rho$$

- Commercial Codes

$$\nabla \cdot (\rho \vec{U} \vec{U}) = \nabla \cdot \bar{\bar{\tau}} - \nabla p_{rgh} + (\rho - \rho_0) \vec{g}$$

Implementation of New Momentum Equation

- Old

UEqn.H

```
// Solve the Momentum equation

tmp<fvVectorMatrix> UEqn
(
    fvm::div(phi, U)
    + turbulence->divDevRhoReff(U)
    ==
    fvOptions(rho, U)
);

UEqn().relax();

fvOptions.constrain(UEqn());

if (simple.momentumPredictor())
{
    solve
    (
        UEqn()
        ==
        fvc::reconstruct
        (
            (
                - ghf*fvc::snGrad(rho)
                - fvc::snGrad(p_rgh)
            ) * mesh.magSf()
        )
    );

    fvOptions.correct(U);
}
```

- New

UEqn.H

```
// Solve the Momentum equation

tmp<fvVectorMatrix> UEqn
(
    fvm::div(phi, U)
    + turbulence->divDevRhoReff(U)
    ==
    (rho - rho0)*g
    + fvOptions(rho, U)
);

UEqn().relax();

fvOptions.constrain(UEqn());

if (simple.momentumPredictor())
{
    solve(UEqn() == -fvc::grad(p_rgh));

    fvOptions.correct(U);
}
```

Implementation of New Momentum Equation

- Modify ϕ_g
 - ϕ_g corresponding to body force $-(\vec{g} \cdot \vec{r})\nabla\rho$

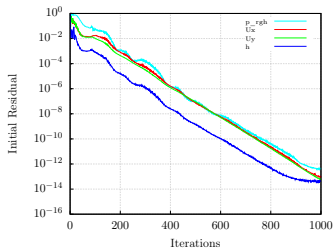
$$\phi_g = -\rho_f \left(\frac{V}{a} \right)_f (\vec{g} \cdot \vec{r})_f \left(\frac{\partial \rho}{\partial n} \right)_f |\vec{S}_f|$$

- ϕ_g corresponding to body force $(\rho - \rho_0)\vec{g}$

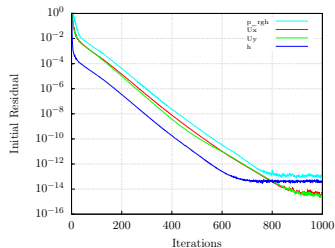
$$\phi_g = \rho_f \left(\frac{V}{a} \right)_f (\rho - \rho_0)_f (\vec{g} \cdot \vec{S}_f)$$

Results

- Residual
- ρ_0 : volume average



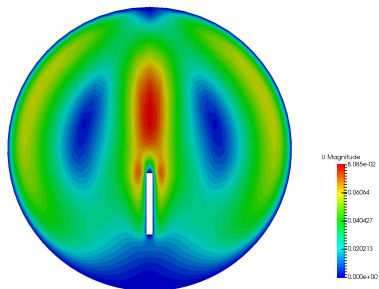
(a) $p_{rgh} = p - \rho(\vec{g} \cdot \vec{r})$



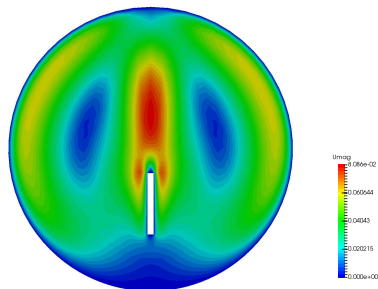
(b) $p_{rgh} = p - \rho_0(\vec{g} \cdot \vec{r})$

Results

- Velocity Magnitude



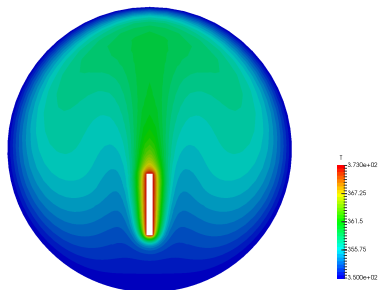
(a) $p_{rgh} = p - \rho(\vec{g} \cdot \vec{r})$



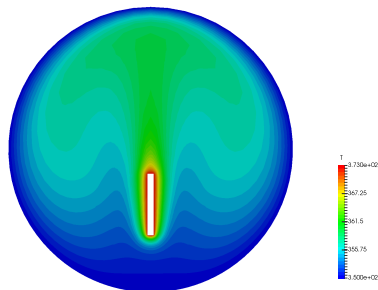
(b) $p_{rgh} = p - \rho_0(\vec{g} \cdot \vec{r})$

Results

- Temperature



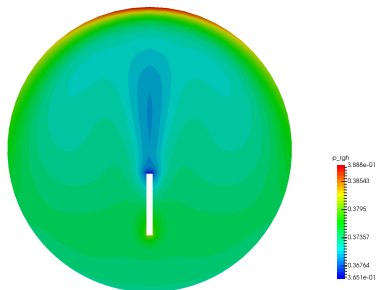
(a) $p_{rgh} = p - \rho(\vec{g} \cdot \vec{r})$



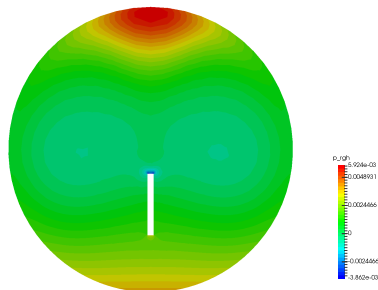
(b) $p_{rgh} = p - \rho_0(\vec{g} \cdot \vec{r})$

Results

- Pressure(p_{rgh})



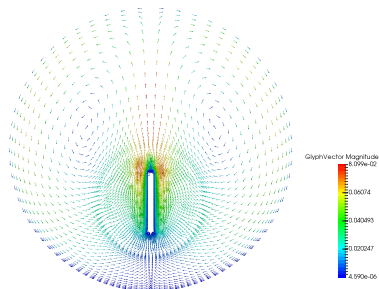
(a) $p_{rgh} = p - \rho(\vec{g} \cdot \vec{r})$



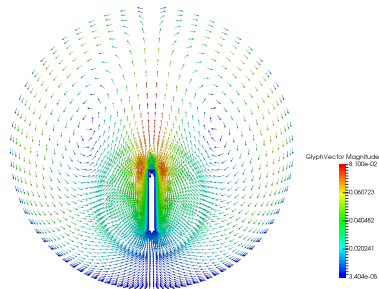
(b) $p_{rgh} = p - \rho_0(\vec{g} \cdot \vec{r})$

Results

- Velocity Vector



(a) $p_{rgh} = p - \rho(\vec{g} \cdot \vec{r})$



(b) $p_{rgh} = p - \rho_0(\vec{g} \cdot \vec{r})$

SIMPLE Algorithm

Pressure-Velocity Coupling

- OpenFOAM's SIMPLE

$$\dot{m}_f = \rho_f \left\{ \frac{H(\vec{U}^*)}{a} \right\}_f \cdot \vec{S}_f - \underbrace{\rho_f \left(\frac{V}{a} \right)_f (\vec{g} \cdot \vec{r})_f \left(\frac{\partial \rho}{\partial n} \right)_f |\vec{S}_f|}_{\phi_g} - \rho_f \left(\frac{V}{a} \right)_f \left(\frac{\partial p}{\partial n} \right)_f |\vec{S}_f|$$

- Original SIMPLE(Rhie-Chow Interpolation)

$$\begin{aligned} \dot{m}_f &= \underbrace{\rho_f \vec{U}_f^* \cdot \vec{S}_f - \rho_f \left(\frac{V}{a} \right)_f |\vec{S}_f| \left\{ \left(\frac{\partial p^*}{\partial n} \right)_f - \vec{n} \cdot \overline{(\nabla p^*)}_f \right\}}_{\text{Rhie-Chow interpolation}} - \rho_f \left(\frac{V}{a} \right)_f \left(\frac{\partial p'}{\partial n} \right)_f |\vec{S}_f| \\ &= \rho_f \vec{U}_f^* \cdot \vec{S}_f + \rho_f \left(\frac{V}{a} \right)_f |\vec{S}_f| \vec{n} \cdot \overline{(\nabla p^*)}_f - \rho_f \left(\frac{V}{a} \right)_f \left(\frac{\partial p}{\partial n} \right)_f |\vec{S}_f| \end{aligned}$$

- $\overline{(\nabla p^*)}_f$ is interpolation of cell gradient

Pressure-Velocity Coupling

- ϕ_g
 - Original SIMPLE algorithm의 \dot{m}_f 는 ϕ_g 를 내포하고 있으므로 경계면에서만 ϕ_g 를 고려한다.

pEqn.H

```

:
:
:
// Add flux due to gravity on all fixedFluxPressure boundaries
forAll(p_rgh.boundaryField(), patchi)
{
    if (p_rgh.boundaryField()[patchi].type() == "fixedFluxPressure")
    {
        phi.boundaryField()[patchi] += phig.boundaryField()[patchi];
    }
}

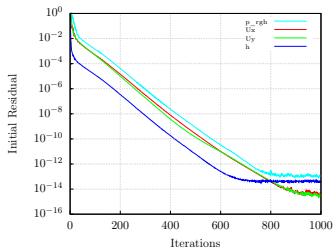
// Update the fixedFluxPressure BCs to ensure flux consistency
setSnGrad<fixedFluxPressureFvPatchScalarField>
(
    p_rgh.boundaryField(),
    (
        phi.boundaryField()
        - fvOptions.relative(mesh.Sf().boundaryField() & U.boundaryField())
        *rho.boundaryField()
    )/(mesh.magSf().boundaryField()*rhorAUf.boundaryField())
);

:
:
:

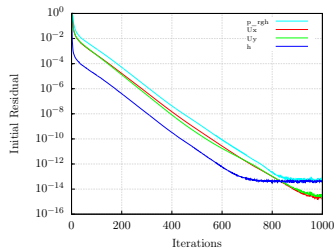
```


Results

- Residual
 - ρ_0 : volume average



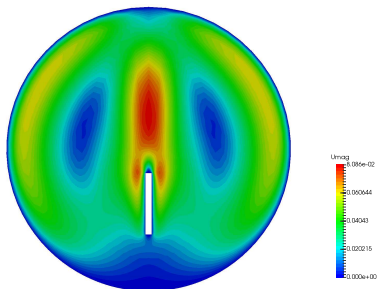
(a) OpenFOAM's SIMPLE



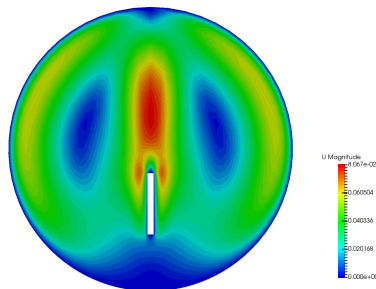
(b) Original SIMPLE

Results

- Velocity Magnitude



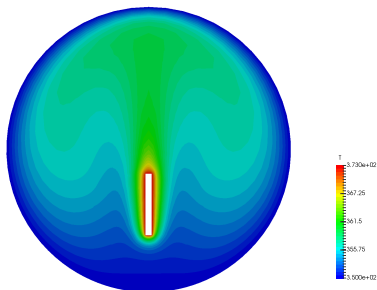
(a) OpenFOAM's SIMPLE



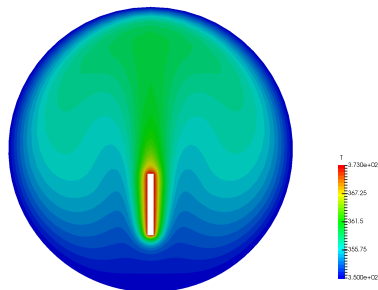
(b) Original SIMPLE

Results

- Temperature



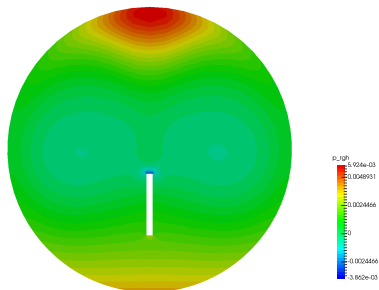
(a) OpenFOAM's SIMPLE



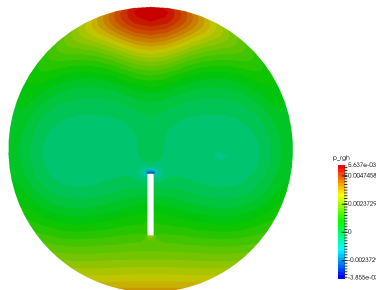
(b) Original SIMPLE

Results

- Pressure(p_rgh)



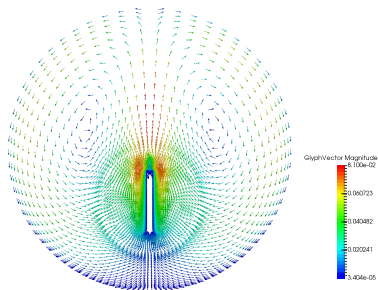
(a) OpenFOAM's SIMPLE



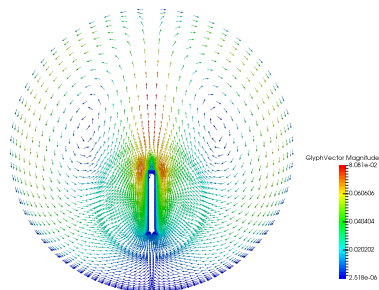
(b) Original SIMPLE

Results

- Velocity Vector



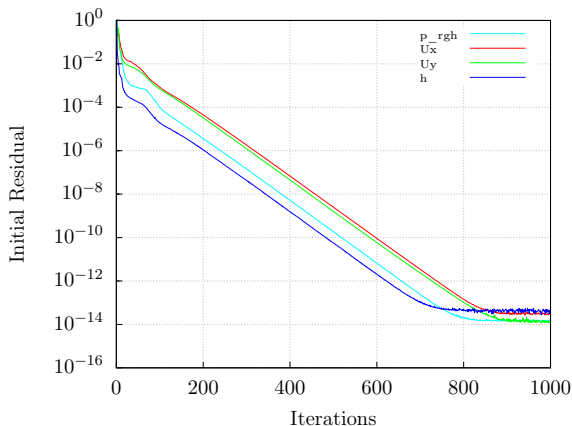
(a) OpenFOAM's SIMPLE



(b) Original SIMPLE

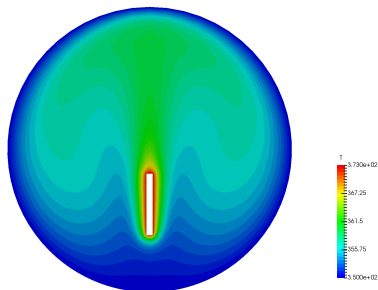
What if we specify operating density(ρ_0) as 0?

- Residual
 - $\rho_0 = 0$

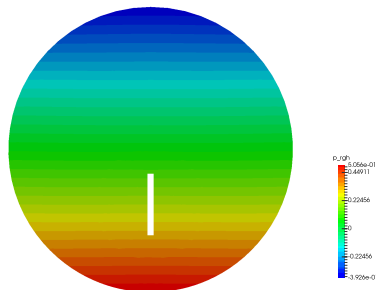


What if we specify operating density(ρ_0) as 0?

- Results



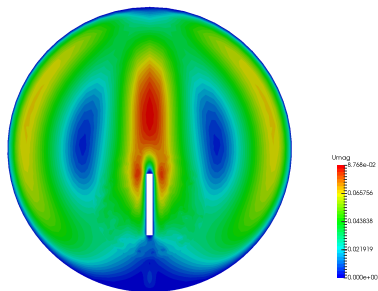
(a) Temperature



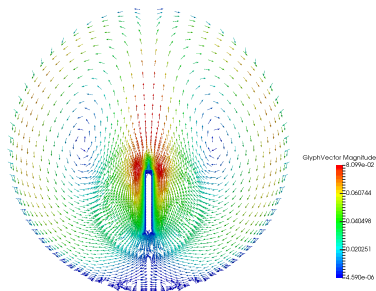
(b) Pressure(p_rgh)

What if we specify operating density(ρ_0) as 0?

- Results



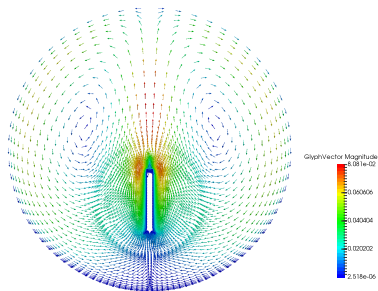
(a) Velocity Magnitude



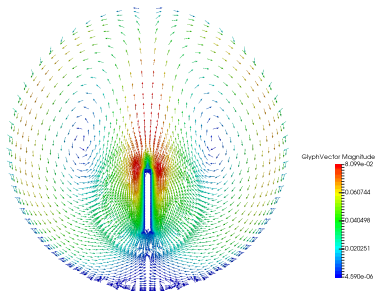
(b) Velocity Vector

What if we specify operating density(ρ_0) as 0?

- Velocity Vector



(a) ρ_0 = volume average



(b) $\rho_0 = 0$

Pressure Gradient in Momentum Equation

Discretization of Pressure Gradient in Momentum Equation

- Momentum Equation

$$\nabla \cdot (\rho \vec{U} \vec{U}) = \nabla \cdot \vec{\bar{\tau}} - \nabla p_{rgh} + (\rho - \rho_0) \vec{g}$$

- $\rho_0 = 0$ 이면 $p_{rgh} = p$

$$\nabla \cdot (\rho \vec{U} \vec{U}) = \nabla \cdot \vec{\bar{\tau}} - \nabla p + \rho \vec{g} \quad (3)$$

- Integral Form

$$\int_{V_P} \left\{ \nabla \cdot (\rho \vec{U} \vec{U}) \right\} dV = \int_{V_P} (\nabla \cdot \vec{\bar{\tau}}) dV - \int_{V_P} (\nabla p) dV + \int_{V_P} (\rho \vec{g}) dV \quad (4)$$

Discretization of Pressure Gradient in Momentum Equation

- Two Different Discretization Methods in OpenFOAM (`fvc::grad(p)`)

- Gauss' Divergence Theorem

- flat face 가정
- face centroid에 대한 Taylor series expansion 포함(first-order approximation)
- face centroid에서의 pressure, p_f , 는 interpolation으로 구함

$$\begin{aligned}\int_{V_P} (\nabla p) dV &= \int_{V_P} (\nabla \cdot p \vec{I}) dV = \oint_{\partial V_P} d\vec{S} \cdot (p \vec{I}) \\ &\approx \sum_f (p \vec{I})_f \cdot \vec{S}_f = \sum_f p_f \vec{S}_f\end{aligned}\tag{5}$$

- Least-Squares Method

- ∇p 를 cell centroid에 대한 Taylor series expansion으로 표현
- first-order approximation
- cell centroid의 정의에 따라 1차항 소거
- cell centroid에서의 pressure gradient, $(\nabla p)_P$, 를 least-squares method로 구함

$$\int_{V_P} (\nabla p) dV \approx V_P (\nabla p)_P\tag{6}$$

Discretization of Pressure Gradient in Momentum Equation

- fvSchemes dictionary example
 - Gauss' Divergence Theorem

```
system/fvSchemes
```

```
gradSchemes
{
    grad(p)      Gauss linear;
}
```

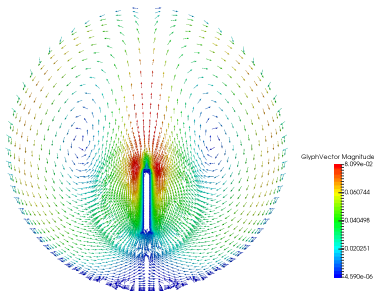
- Least-Squares Method

```
system/fvSchemes
```

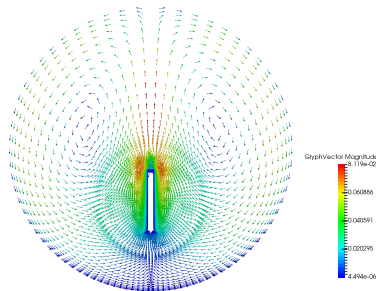
```
gradSchemes
{
    grad(p)      leastSquares;
}
```

Discretization of Pressure Gradient in Momentum Equation

- Least-Squares Method
 - 벡터의 방향이 상당부분 개선됨



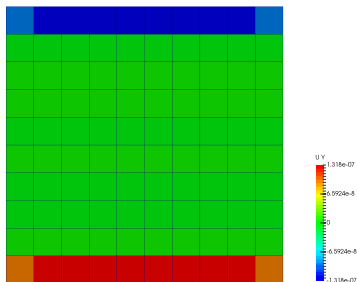
(a) Gauss linear



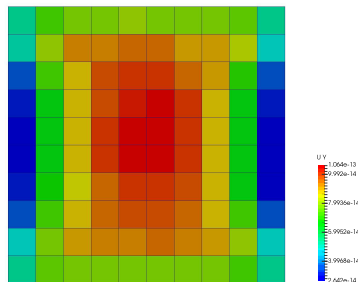
(b) leastSquares

Discretization of Pressure Gradient in Momentum Equation

- Least-Squares Method의 문제점
 - 벽면에서 첫번째 cell의 gradient 계산 오류
 - `fixedFluxPressure` 경계조건과 부합하지 않음



(a) leastSquares



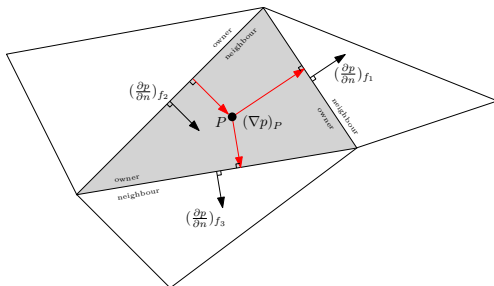
(b) Gauss linear

Another Way of Pressure Gradient Calculation in OpenFOAM

- `fvc::reconstruct (fvc::snGrad (p) *mesh.magSf ())`

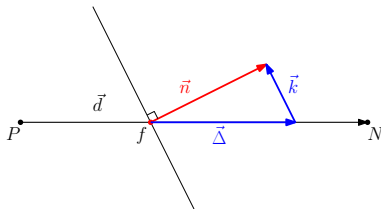
$$\int_{V_P} (\nabla p) dV \approx V_P (\nabla p)_P$$

$$\left\{ \sum_f \rho_f \left(\frac{V}{a} \right)_f (\vec{n} \otimes \vec{S}_f) \right\} \cdot (\nabla p)_P = \sum_f \rho_f \left(\frac{V}{a} \right)_f \left(\frac{\partial p}{\partial n} \right)_f \vec{S}_f$$



Another Way of Pressure Gradient Calculation in OpenFOAM

- `fvc::snGrad(p)`
- non-orthogonal correction



- Split unit normal vector(\vec{n}) into two parts:

$$\vec{n} = \vec{\Delta} + \vec{k}$$

then,

$$\left(\frac{\partial p}{\partial n} \right)_f = |\vec{\Delta}| \frac{p_N - p_P}{|\vec{d}|} + \underbrace{\vec{k} \cdot (\nabla p)_f}_{\text{non-orthogonal correction}}$$

Another Way of Pressure Gradient Calculation in OpenFOAM

- `fvc::snGrad(p)`
 - correction을 위해 필요한 cell gradient 처리 방법 수정 필요

correctedSnGrad.C

```

:
:
Foam::fv::correctedSnGrad<Type>::fullGradCorrection
(
    const GeometricField<Type, fvPatchField, volMesh>& vf
) const
{
    const fvMesh& mesh = this->mesh();
    // construct GeometricField<Type, fvsPatchField, surfaceMesh>
    tmp<GeometricField<Type, fvsPatchField, surfaceMesh> > tssf =
        mesh.nonOrthCorrectionVectors()
        & linear<typeName> outerProduct<vector, Type>::type>(mesh).interpolate
        (
            gradScheme<Type>::New
            (
                mesh,
                mesh.gradScheme("grad(" + vf.name() + ')')
            )().grad(vf, "grad(" + vf.name() + ')')
        );
    tssf().rename("snGradCorr(" + vf.name() + ')');
    return tssf;
}

:
:

```

Another Way of Pressure Gradient Calculation in OpenFOAM

- `fvc::snGrad(p)`
 - objectRegistry에 등록된 gradient field를 찾아서 사용하도록 수정

correctedSnGrad.C

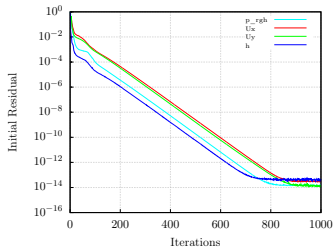
```
.
.
.
tmp
<
    GeometricField
    <
        typename outerProduct<vector, Type>::type,
        fvPatchField,
        volMesh
    >
> tgradVf
(
    mesh.lookupObject
    <
        GeometricField
        <
            typename outerProduct<vector, Type>::type,
            fvPatchField,
            volMesh
        >
> ("grad" + vf.name())
);

.
.
```

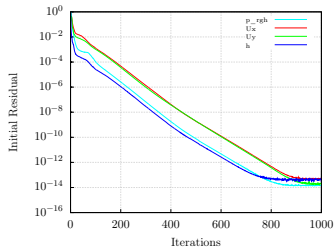
Results

- Residual

- $\rho_0 = 0$



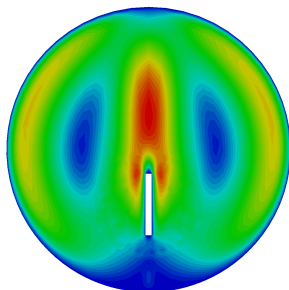
(a) Gauss linear



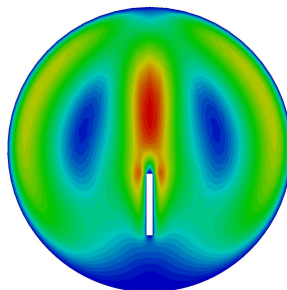
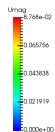
(b) reconstruct snGrad

Results

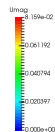
- Velocity



(a) Gauss linear

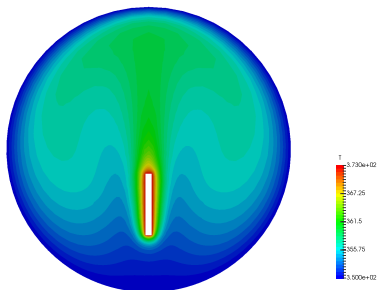


(b) reconstruct snGrad

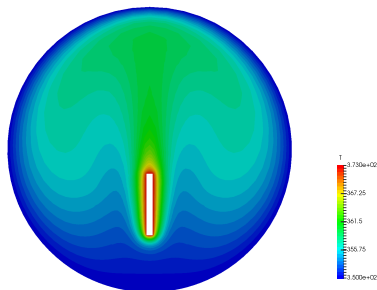


Results

- Temperature



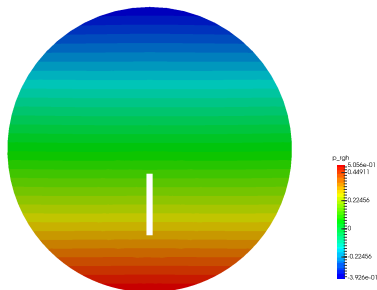
(a) Gauss linear



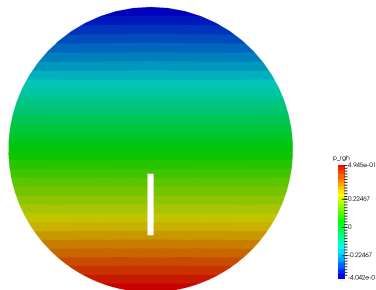
(b) reconstruct snGrad

Results

- Pressure(p_{rgh})



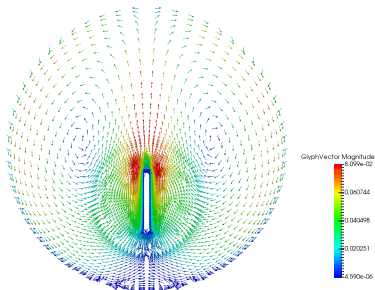
(a) Gauss linear



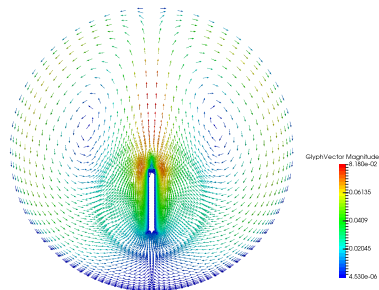
(b) reconstruct snGrad

Results

- Velocity Vector



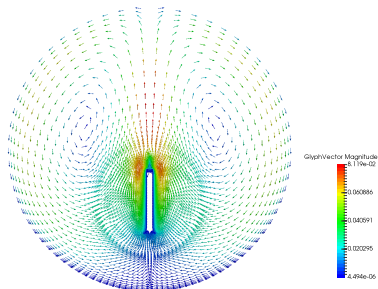
(a) Gauss linear



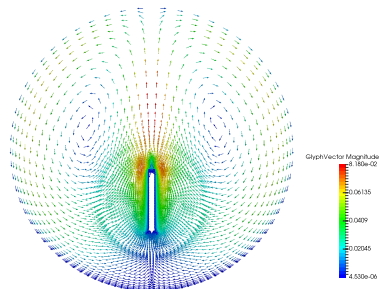
(b) reconstruct snGrad

Results

- Velocity Vector



(a) leastSquares



(b) reconstruct snGrad

부록

Limited Gradient 사용의 문제점

Limited Gradient 사용의 문제점

- cellLimited gradient scheme
 - dictionary

```
system/fvSchemes
```

```
gradSchemes
{
    grad(p)          cellLimited Gauss linear 1.0;
}
```

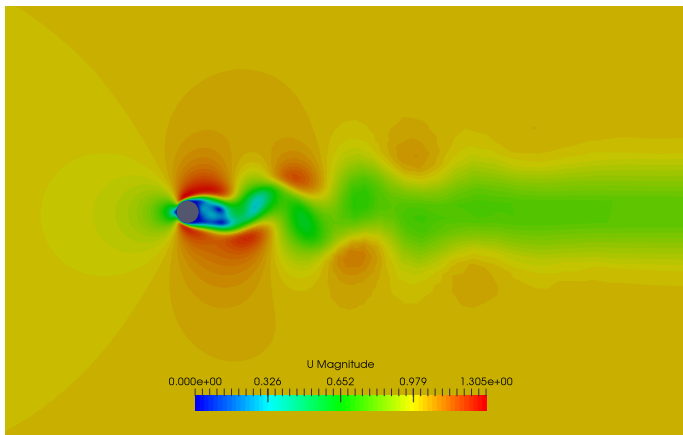
- `solve(UEqn() == -fvc::grad(p));` 의 의미

$$\int_{V_P} \left\{ \nabla \cdot (\rho \vec{U} \vec{U}) \right\} dV = \int_{V_P} (\nabla \cdot \vec{\tau}) dV - \underbrace{\Psi \int_{V_P} (\nabla p) dV}_{???} + \int_{V_P} (\rho \vec{g}) dV$$

Ψ : slope limiter

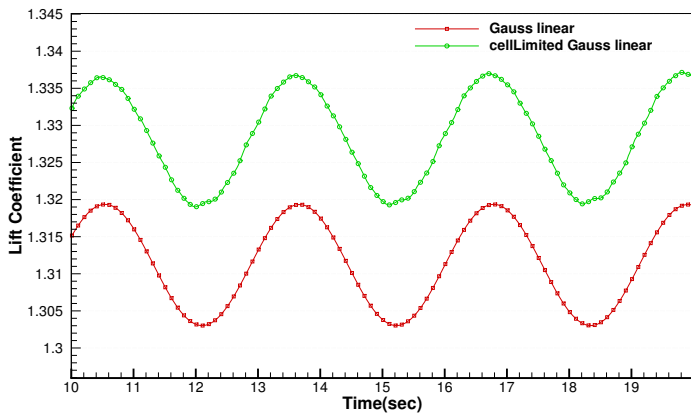
Limited Gradient 사용의 문제점

- laminar flow past a circular cylinder



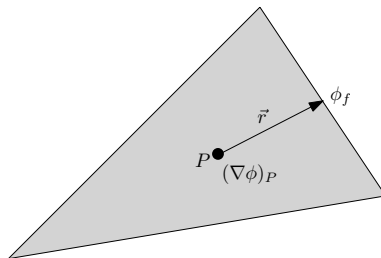
Limited Gradient 사용의 문제점

- Lift Coefficient



Slope Limiter

- Face value를 reconstruct할 때 사용



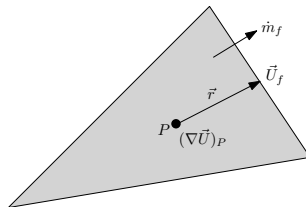
$$\phi_f = \phi_P + \vec{r} \cdot \{\Psi(\nabla \phi)_P\}$$

Slope Limiter

- Convection Term 이산화

$$\int_{V_P} \{ \nabla \cdot (\rho \vec{U} \vec{U}) \} dV \approx \sum_f \dot{m}_f \vec{U}_f$$

- linearUpwind



$$\vec{U}_f = \vec{U}_P + \vec{r} \cdot \{ \Psi (\nabla \vec{U})_P \}$$

Slope Limiter

- fvSchemes dictionary

system/fvSchemes

```
gradSchemes
{
    default          Gauss linear;
    grad(U)          cellLimited Gauss linear 1.0;
}

divSchemes
{
    default          Gauss upwind;
    div(phi,U)       Gauss linearUpwind grad(U);

    :
    :

    div((muEff*dev2(T(grad(U)))) Gauss linear;
}
```