

# **Development of Automated Aerodynamic Analysis Process Using Open-source Software**

**2023. 07.12  
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- **Automated Aerodynamic Analysis Process**
- **Benchmark Test**
- **Conclusion**

# Introduction

## ○ Missile Aerodynamic Design

- Aerodynamic performance evaluation with data using **multiple flow conditions**
  - ✓ Stability, Maneuverability
- Require **evaluation for a number of configuration** in design stage

## ○ Aerodynamic Solver

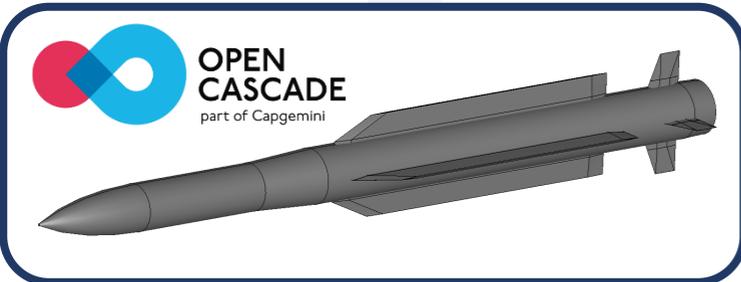
- Semi-empirical code (Missile DATCOM, AeroPrediction)
  - ✓ Low computational cost, Low accuracy
- CFD
  - ✓ High computational cost, High accuracy
  - ✓ Performing **tedious tasks of geometry and mesh generation**

# Introduction

## ○ Objective

- Develop automated aerodynamic analysis process for missile design
- Consists of geometry, mesh, flow analysis and post-processing modules
- Aim to minimize user intervention in each module
- All modules are developed using open-source software

### Geometry



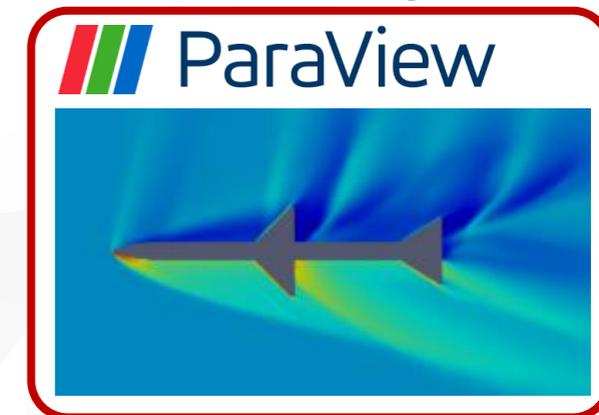
### Mesh



### Flow Analysis



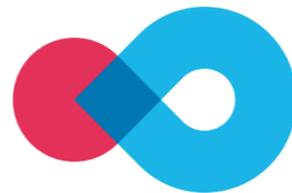
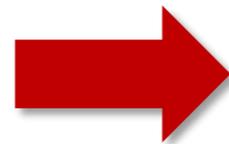
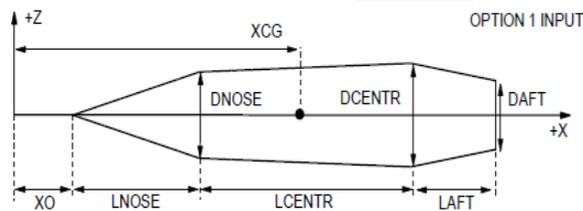
### Post-processing



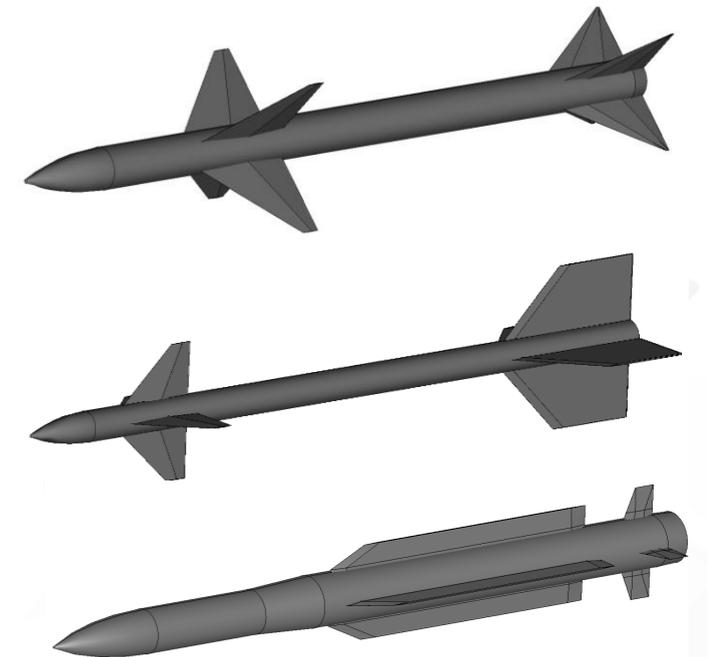
# Automated Aerodynamic Analysis Process

## ○ Geometry Modeling

- Adopt geometry definition of Missile DATCOM
  - ✓ Axisymmetric Body + Multiple Finset
  - ✓ Fin Deflection for aerodynamic control
- Geometry representation using **OpenCASCADE**
- Export CAD to STEP file format



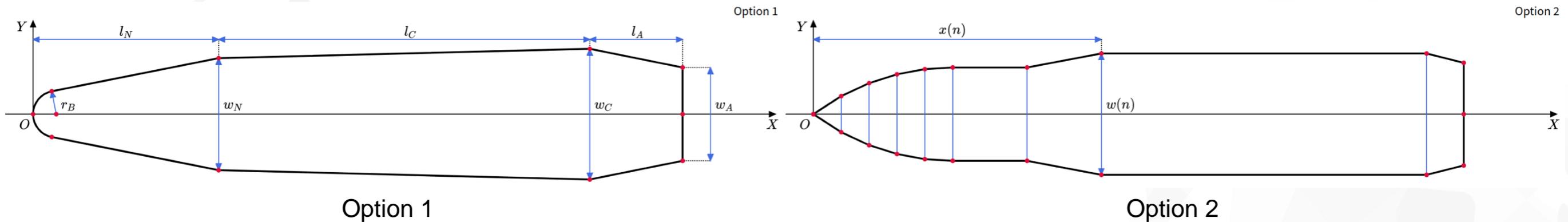
**OPEN  
CASCADE**  
part of Capgemini



# Automated Aerodynamic Analysis Process

## ○ Geometry Modeling – Body

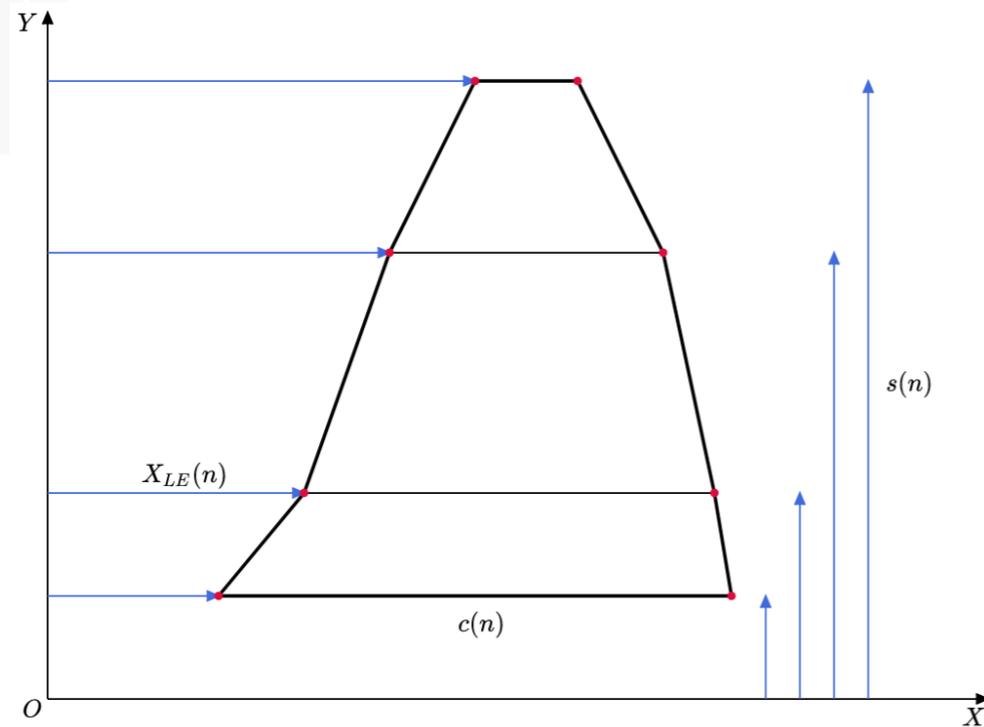
- Option 1 : Composition of Nose, Centerbody, Afterbody
  - ✓ Nose : Cone, Ogive, Power, Haack, Karman
  - ✓ Afterbody : Cone, Ogive
- Option 2 : Longitudinal Coordinate (X, R)



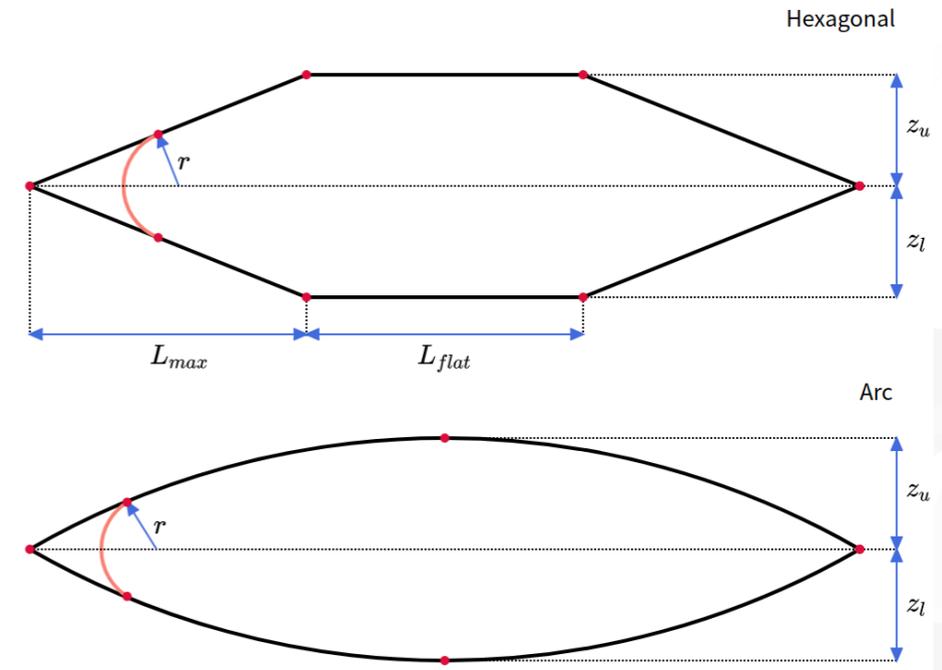
# Automated Aerodynamic Analysis Process

## ○ Geometry Modeling – Finset

- Planform : Consist of position of leading edge, chord, semispan
- Airfoil : Support Hex, Arc and NACA 4 series



Planform



Airfoil (Hex, Arc)

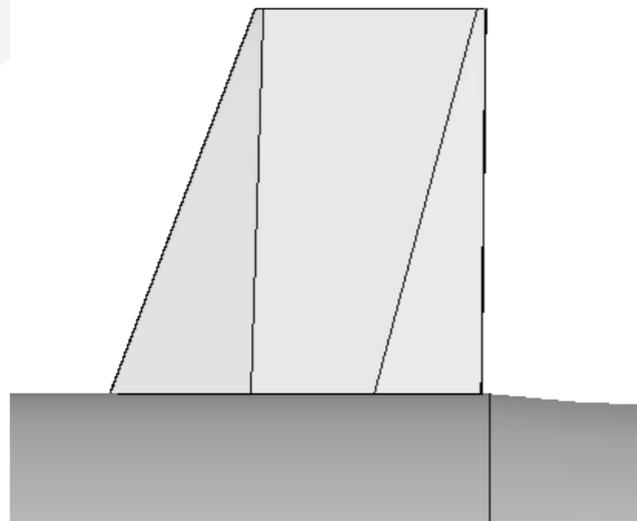
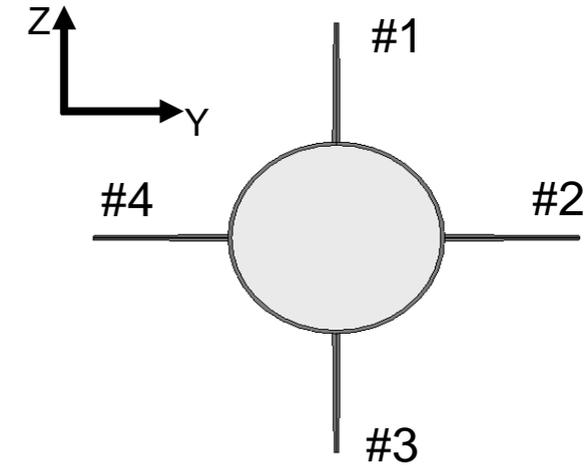
# Automated Aerodynamic Analysis Process

## ○ Geometry Modeling – Fin Deflection

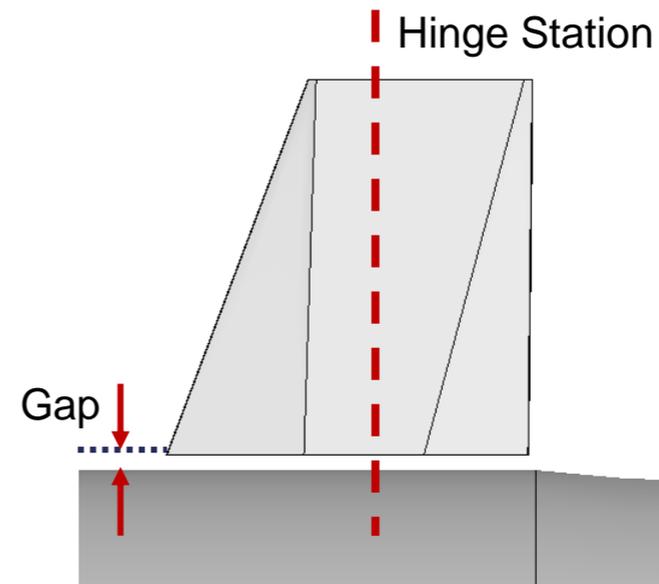
- Deflection angle sign convention

$$\delta_P = \frac{\delta_2 - \delta_4}{2} \quad \delta_Y = \frac{\delta_3 - \delta_1}{2} \quad \delta_R = \frac{\delta_1 + \delta_2 + \delta_3 + \delta_4}{4}$$

- Apply gap between body and fin to generate volume mesh



without Deflection



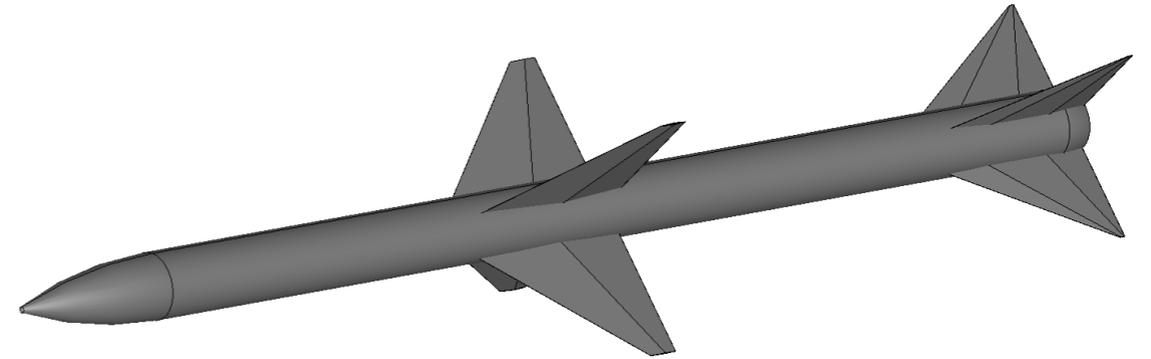
with Deflection

# Automated Aerodynamic Analysis Process

## ○ Geometry Modeling – Example

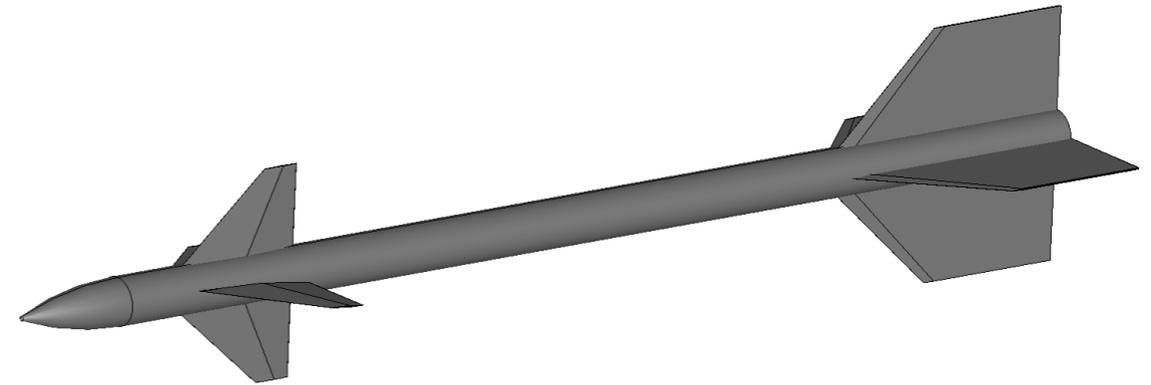
### 1. NASA TP 1078 (Sparrow)

- ✓ Body : Nose + Centerbody + Afterbody



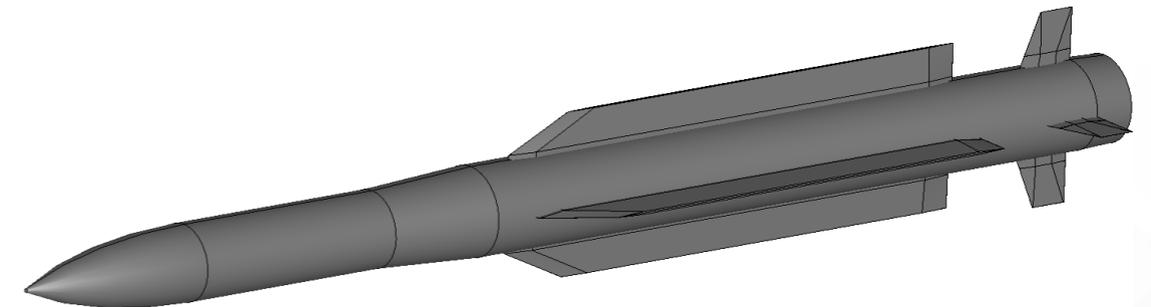
### 2. NASA TP 2157

- ✓ Body : Nose + Centerbody



### 3. NASA TM 2005

- ✓ Body : Longitudinal Coordinate



# Automated Aerodynamic Analysis Process

## ○ Mesh Generation

- Generate unstructured **Tetrahedral** with **prism layer**
- Use **NETGEN** algorithm in **SALOME** software
- Export Mesh to I-Deas Universal unv format
  - ✓ Convertible to OpenFOAM format using **IdeasUnvToFoam** utility



# Automated Aerodynamic Analysis Process

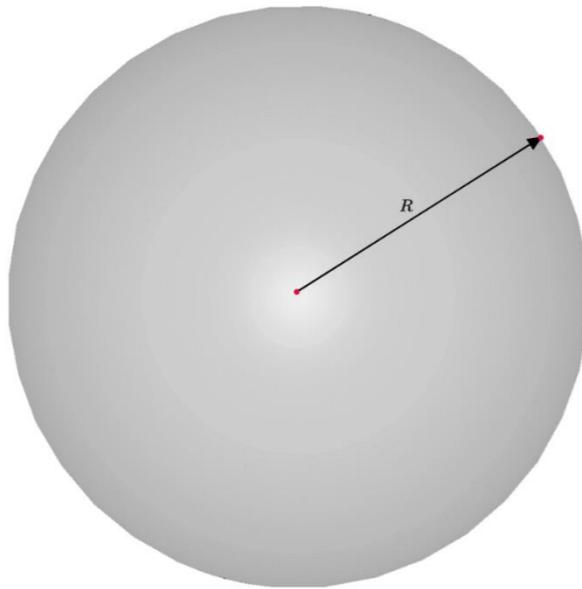
## ○ Mesh Generation – Parameter

- Computational Domain & Refinement Region
  - ✓ Position, Radius, Height
- Mesh Size
  - ✓ Max size, Min size, Growth rate
- Prism Layer
  - ✓ Number of Layer, First layer height, Stretch Factor

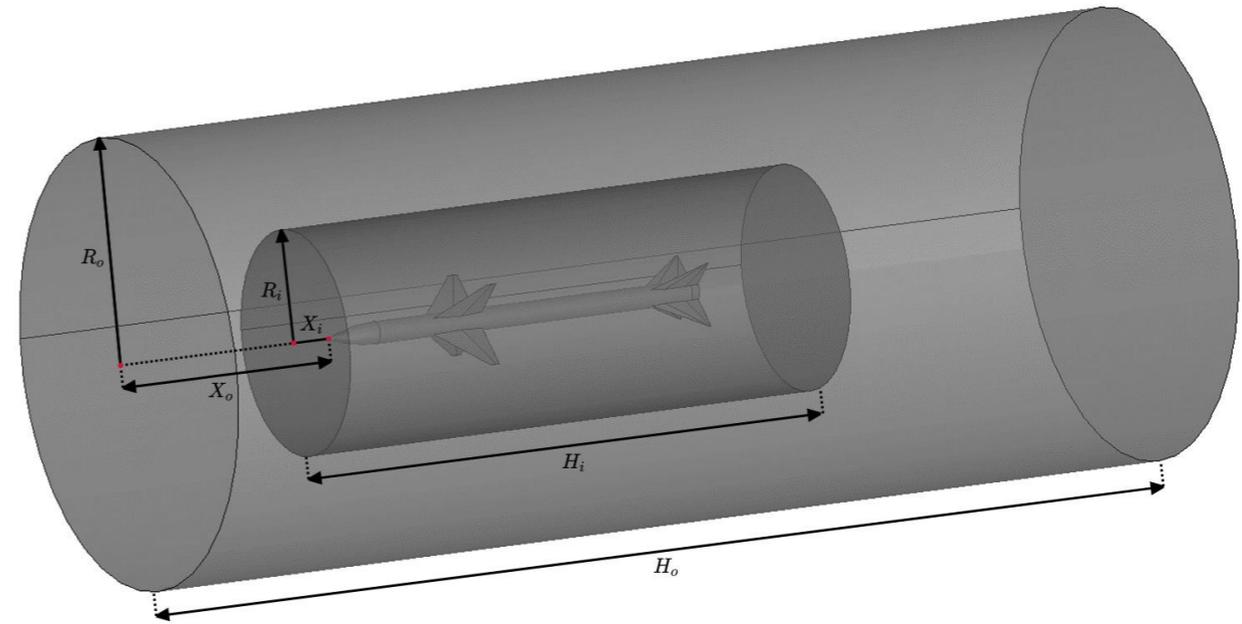
# Automated Aerodynamic Analysis Process

## ○ Mesh Generation – Domain & Refinement Region

- Use spherical computational domain
- Use two cylindrical refinement region
  - ✓ Capture Shock and wake flow accurately
  - ✓ Guarantee consistent mesh quality regardless of geometry changes



Computational Domain

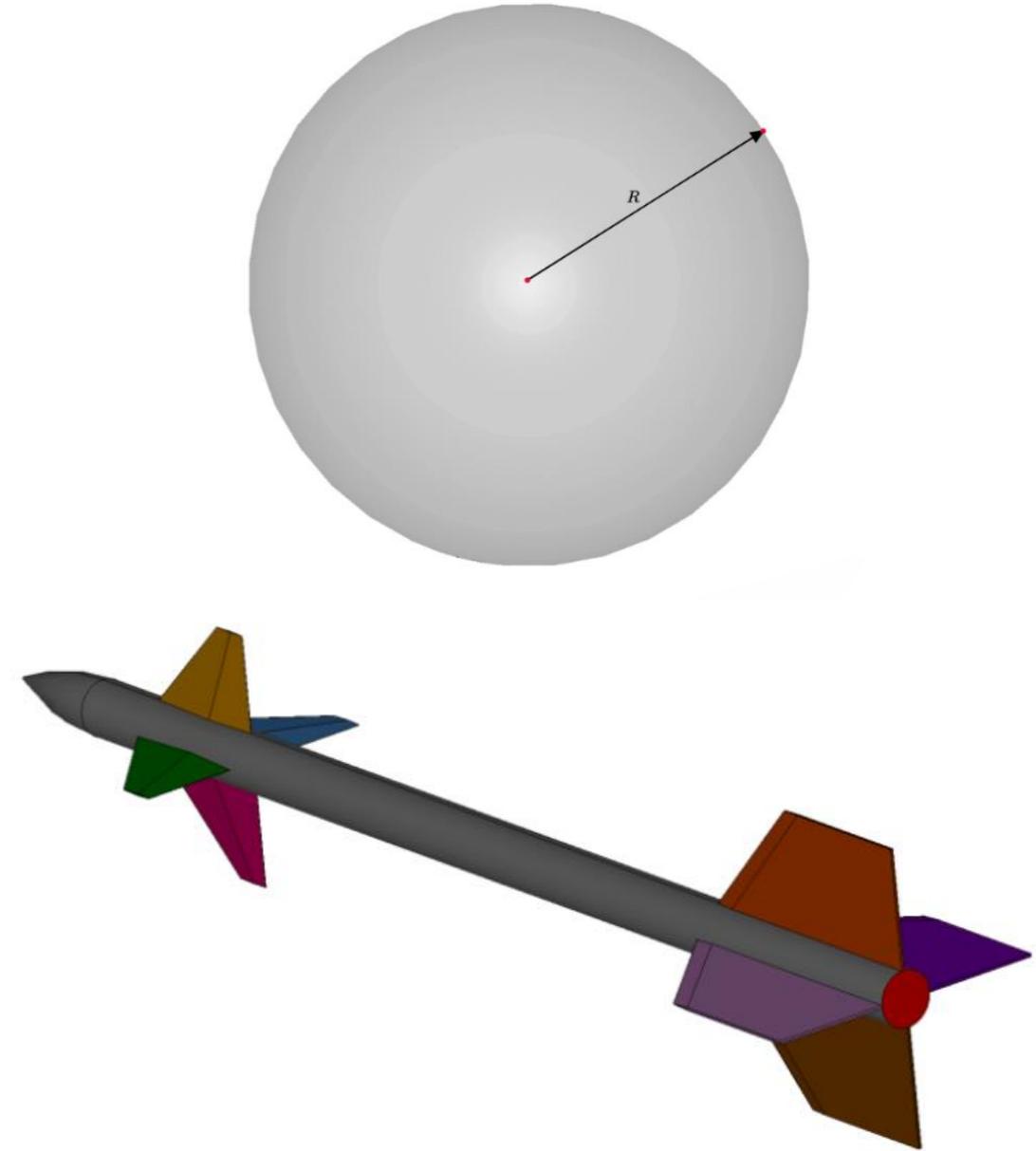


Refinement Region

# Automated Aerodynamic Analysis Process

## ○ Mesh Generation – Grouping

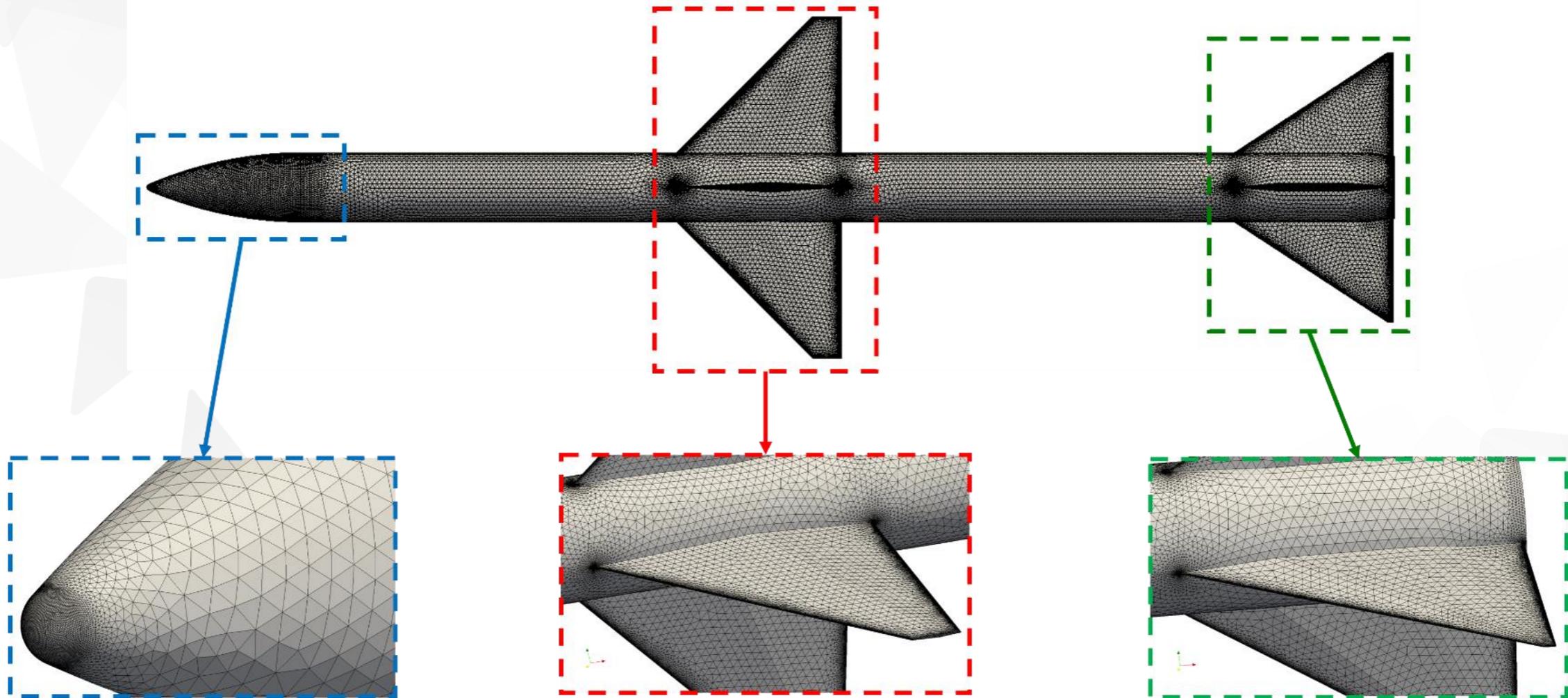
- Search & Group face based on geometric parameter
  - ✓ Computational Domain
  - ✓ Missile Component
- Used for **face refinement**
  - ✓ Nose
  - ✓ Leading edge and trailing edge of Finset
- Used for **setting boundary & initial condition** for flow analysis
- Grouping information is saved when exporting volume mesh



# Automated Aerodynamic Analysis Process

- **Mesh Generation – Example**

- Surface Mesh



# Automated Aerodynamic Analysis Process

## ○ Flow Analysis

- Use **TSLAeroFoam** Solver
  - ✓ Density-based compressible coupled solver
- Develop Python script for pre-processing automation
  - ✓ Using same mesh for multiple flow conditions
  - ✓ Performing mesh conversion and decomposition process only once
  - ✓ Save on storage usage

# Automated Aerodynamic Analysis Process

## ○ Flow Analysis – Parameter

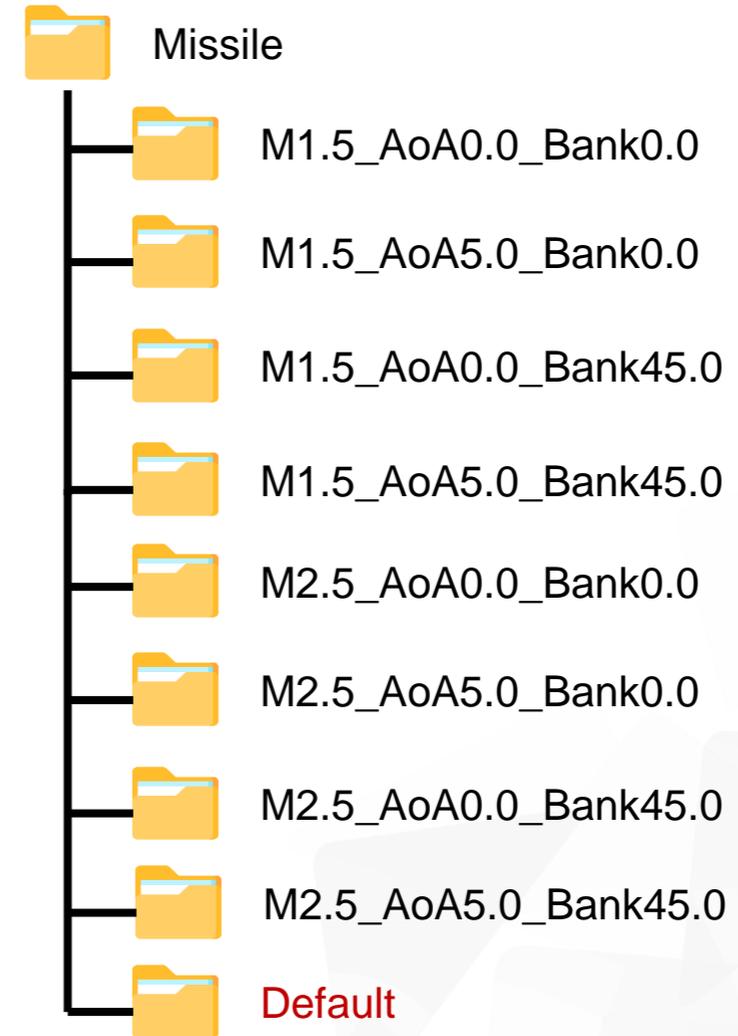
- Flow Conditions
  - ✓ Mach Number\*
  - ✓ Static Pressure (Pa)
  - ✓ Static Temperature (K)
  - ✓ Angle of attack (deg)\*
  - ✓ Bank angle (deg)\*

\* Multiple inputs available

# Automated Aerodynamic Analysis Process

## ○ Flow Analysis – Directory Setting

- Set the directory name with the entered flow conditions
  - ✓ Mach : 2.5, AoA = 5°, Bank 0° : M2.5\_AoA5.0\_Bank0.0
- Default Directory
  - ✓ All cases use same volume mesh and setting file
  - ✓ Store **const** and **system** directory



# Automated Aerodynamic Analysis Process

## ○ Flow Analysis – Mesh Converting

- IdeasUnvToFoam is used for mesh converting
- All boundaries are set as **patch** type by default
- **Modify type** of missile components surface to **wall**

```
Forebody
{
    type                patch;
    nFaces              99211;
    startFace           43960821;
}
Base
{
    type                patch;
    nFaces              3770;
    startFace           44060032;
}
Finset1_Panel1
{
    type                patch;
    nFaces              45857;
    startFace           44063802;
}
```



```
Forebody
{
    type                wall;
    nFaces              99211;
    startFace           43960821;
}
Base
{
    type                wall;
    nFaces              3770;
    startFace           44060032;
}
Finset1_Panel1
{
    type                wall;
    nFaces              45857;
    startFace           44063802;
}
```

# Automated Aerodynamic Analysis Process

## ○ Flow Analysis – Mesh Decomposing

- **Modify the content of files** in **0** directory in processor directory
  - ✓ Search Domain keyword
  - ✓ Change Mach number and flow direction
- **Apply symbolic link** in **const** directory in processor directory
  - ✓ Save storage space

```
Domain
{
    type            farfieldRiemann;
    flowDir        ( 1 0 0 );
    TInf           281.651;
    MInf           1.5;
    pInf           89876.3;
    value          nonuniform 0();
}
```

Processor0 / 0 / U



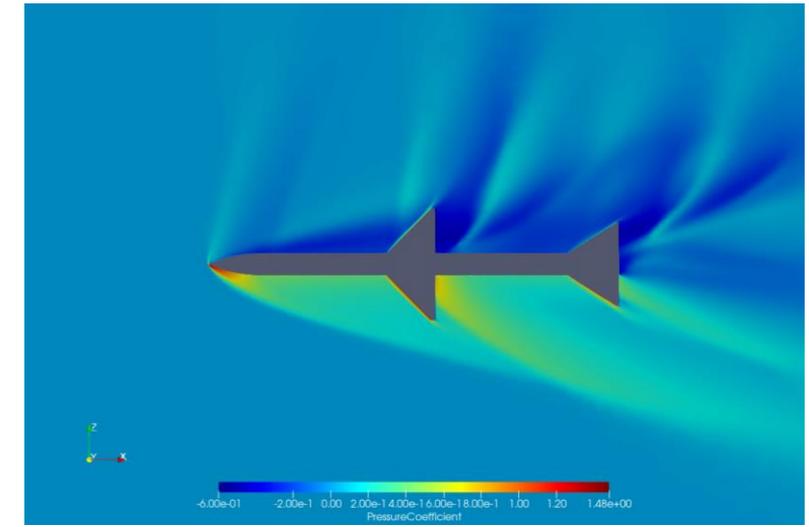
```
Domain
{
    type            farfieldRiemann;
    flowDir        ( 0.9993908270190958 -0.0 0.03489949670250097);
    TInf           281.651;
    MInf           1.5;
    pInf           89876.3;
    value          nonuniform 0();
}
```

Processor0 / 0 / U (Modified)

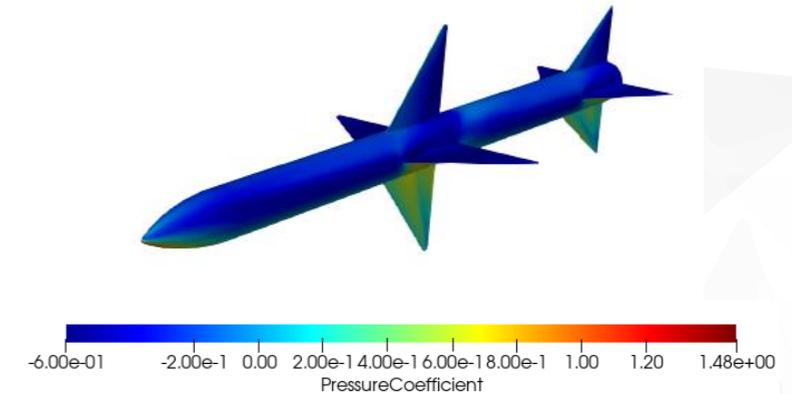
# Automated Aerodynamic Analysis Process

## ○ Post-processing

- Use **ParaView** software to extract image of flow field
- Generate **contour images** for the X-Z and X-Y planes
  - ✓ Set camera position based on geometry parameter
  - ✓ Mach, Static pressure, Static temperature field
- Generate images for the missile surfaces
  - ✓ Fixed camera direction to Isometric view



Contour Image



Surface Image

# Benchmark Test

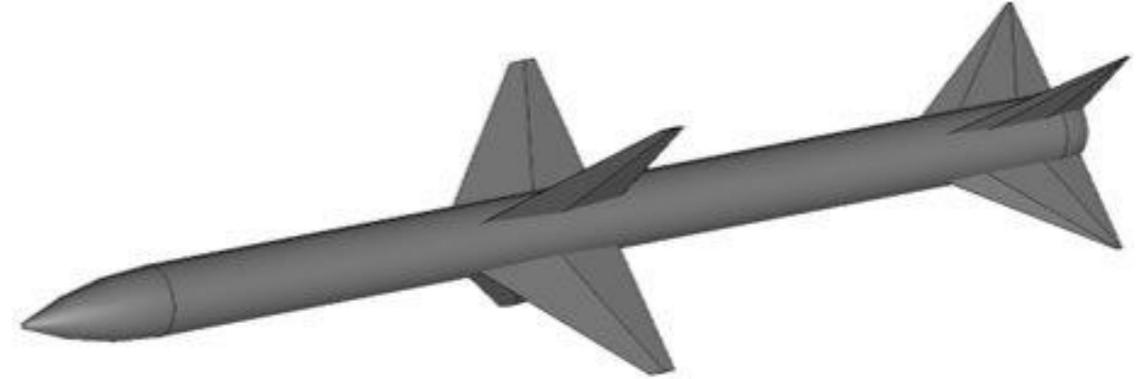
## ○ Case 1 (Sparrow)

- Geometry

- ✓ Body : Nose+ Centerbody + Afterbody
- ✓ Finset : X Configuration

- Flow Condition

- ✓ Mach Number : 1.5
- ✓ Static Pressure (Pa) : 18114.8
- ✓ Static Temperature (K) : 233.793
- ✓ Angle of attack (°) : 0, 5, 11, 17, 23, 27, 32

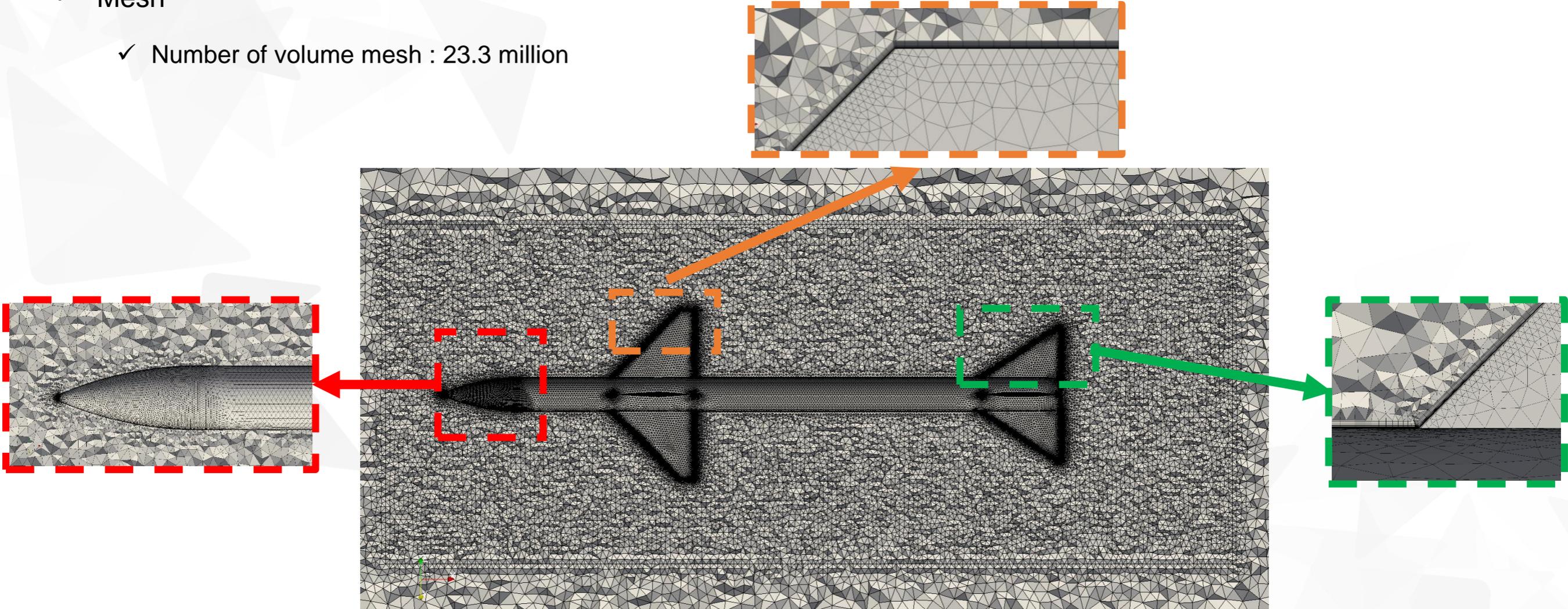


# Benchmark Test

- **Case 1 (Sparrow)**

- Mesh

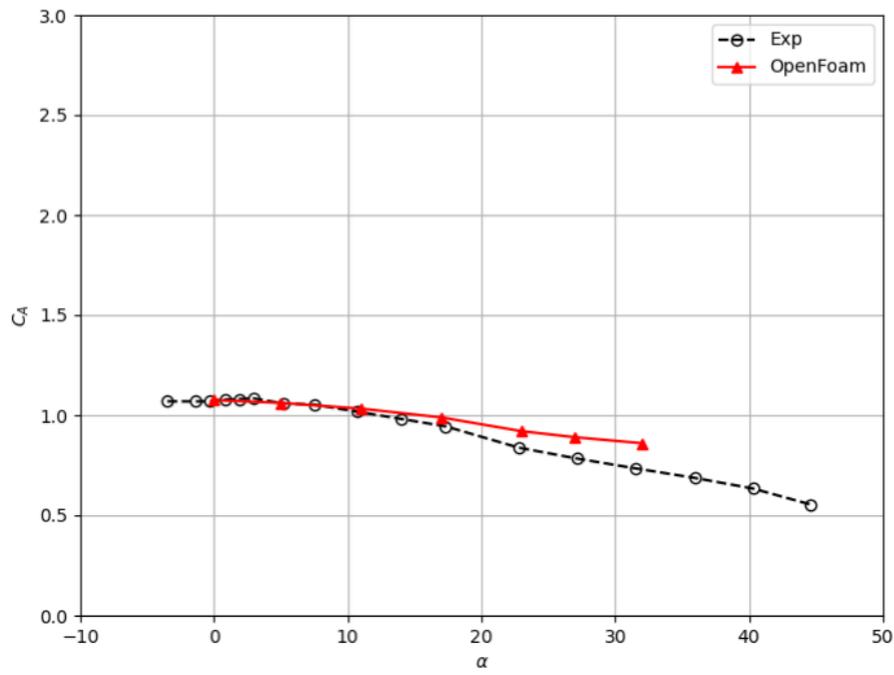
- ✓ Number of volume mesh : 23.3 million



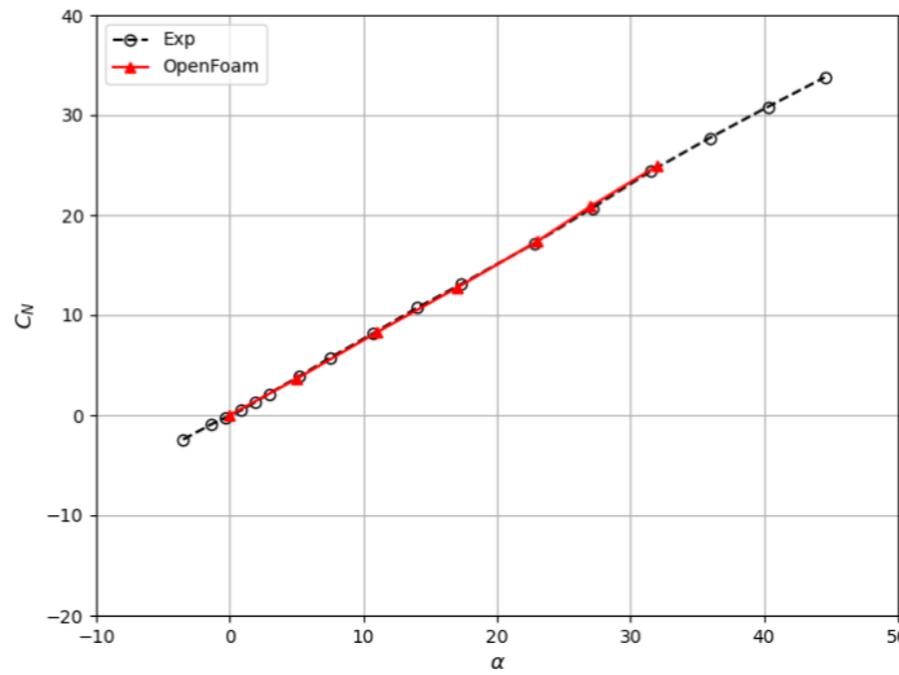
# Benchmark Test

## ○ Case 1 (Sparrow)

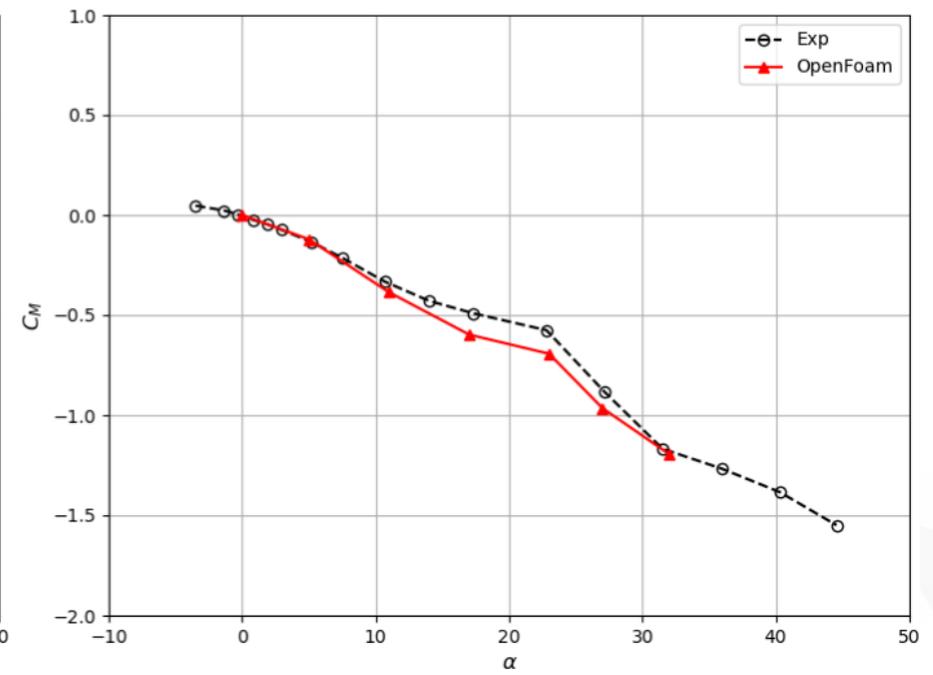
- Overpredict axial force at high angle of attack
- Normal force and pitching moment are in good agreement



Axial Force Coefficient



Normal Force Coefficient

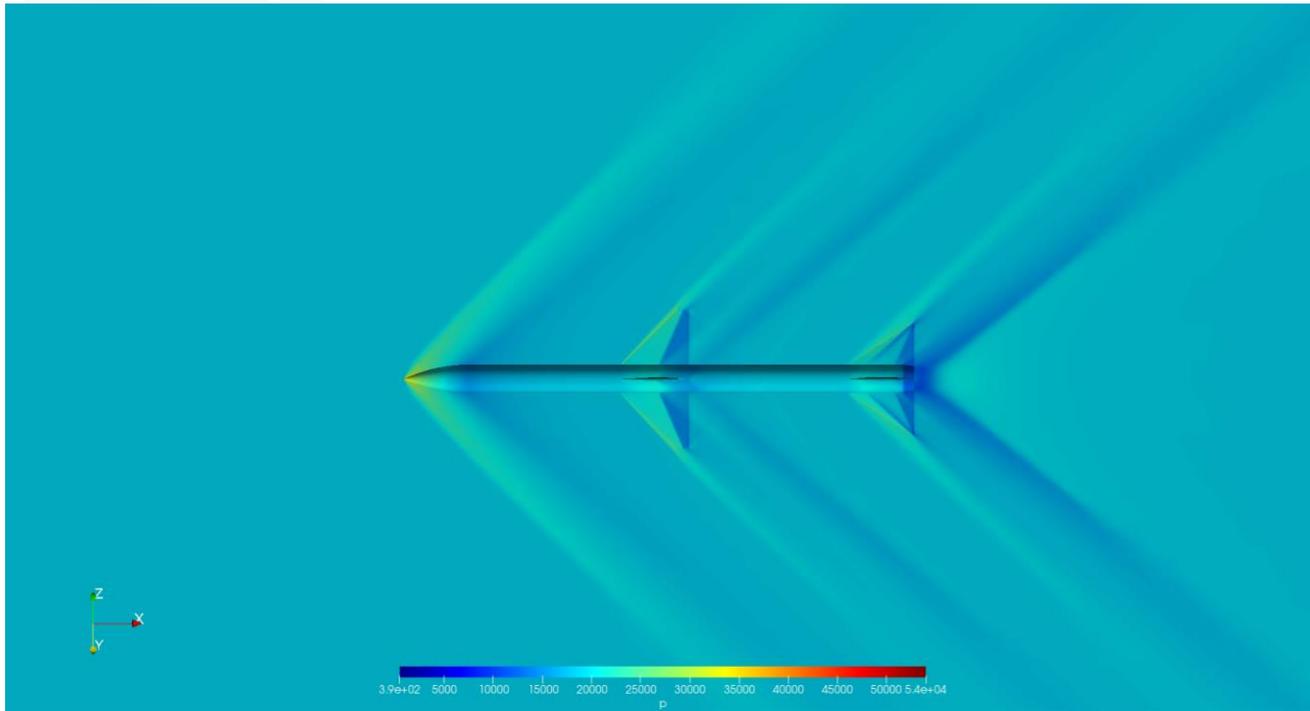


Pitching Moment Coefficient

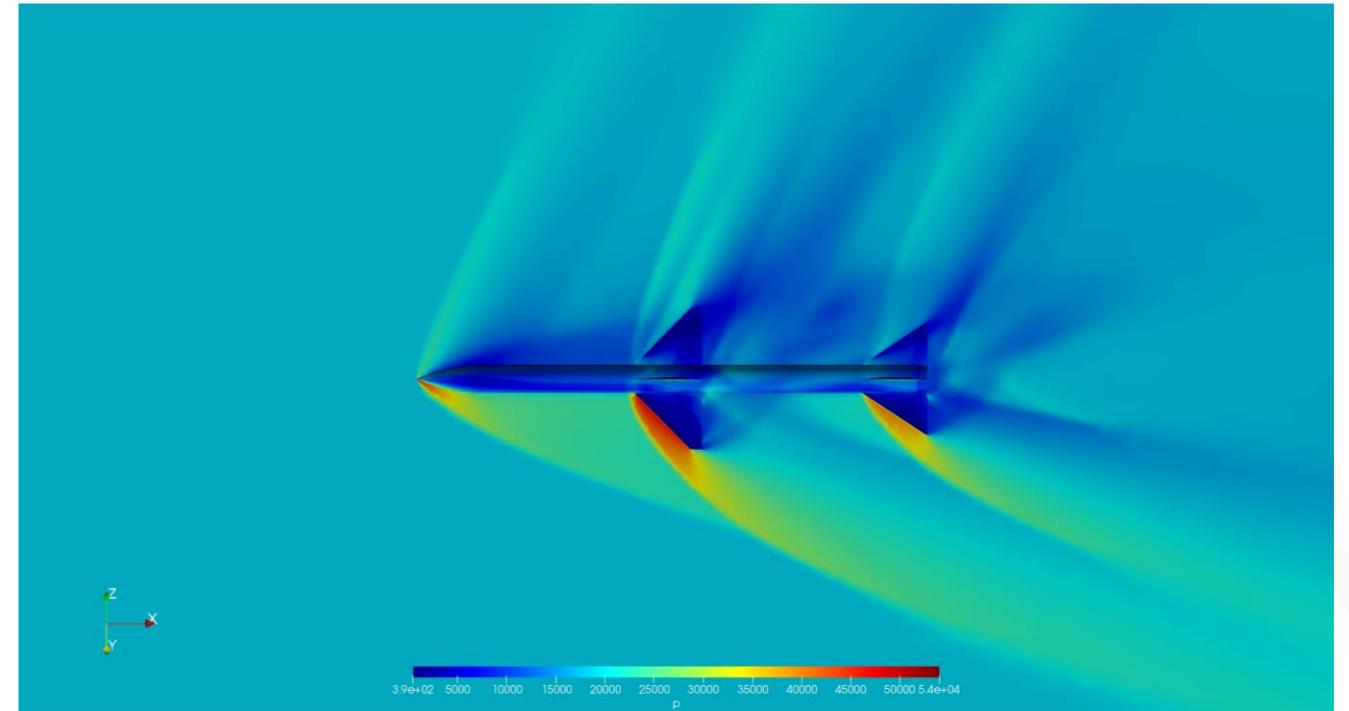
# Benchmark Test

- **Case 1 (Sparrow)**

- Shock wave and wake flow are captured clearly by the use of the refinement regions



AoA = 0°



AoA = 32°

# Benchmark Test

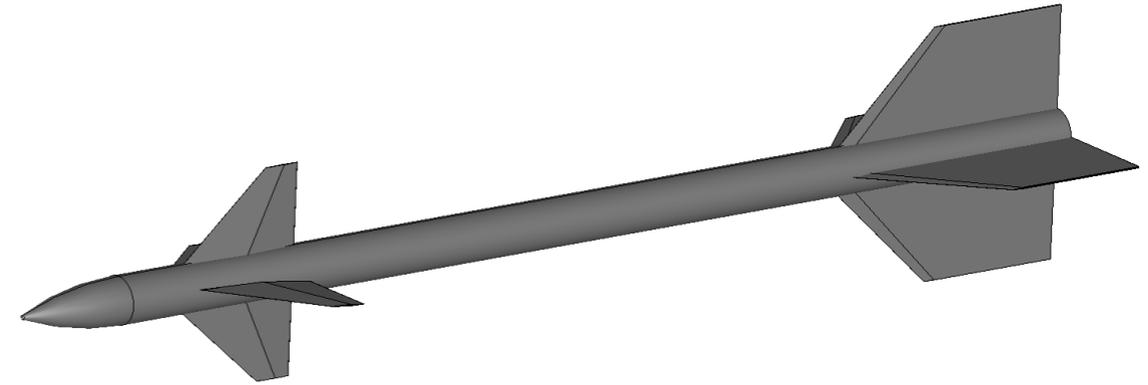
## ○ Case 2 (NASA TP 2157)

- Geometry

- ✓ Body : Nose+ Centerbody
- ✓ Finset : + Configuration

- Flow Condition

- ✓ Mach Number : 3.5
- ✓ Static Pressure (Pa) : 1696.55
- ✓ Static Temperature (K) : 94.2029
- ✓ Angle of attack (°) : -4, 0, 4, 10, 14, 18

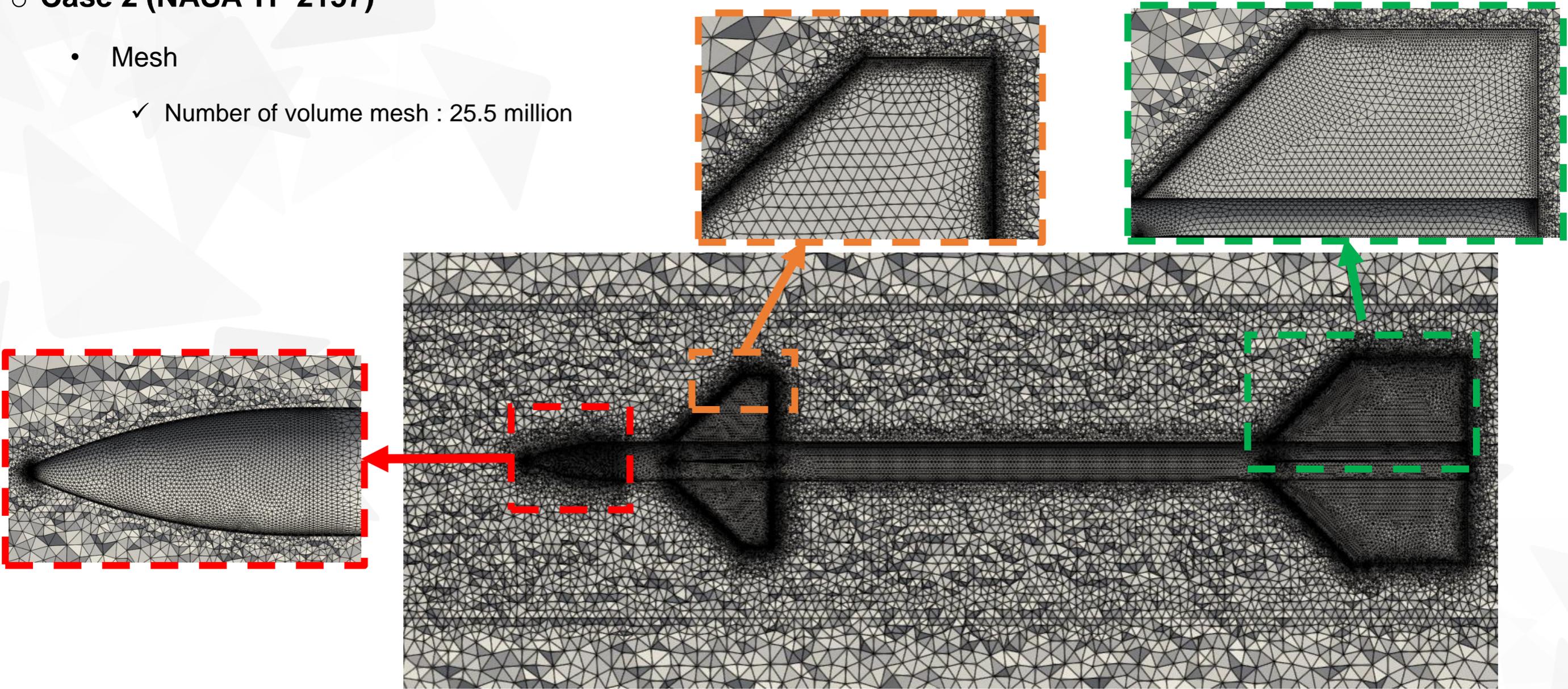


# Benchmark Test

- **Case 2 (NASA TP 2157)**

- Mesh

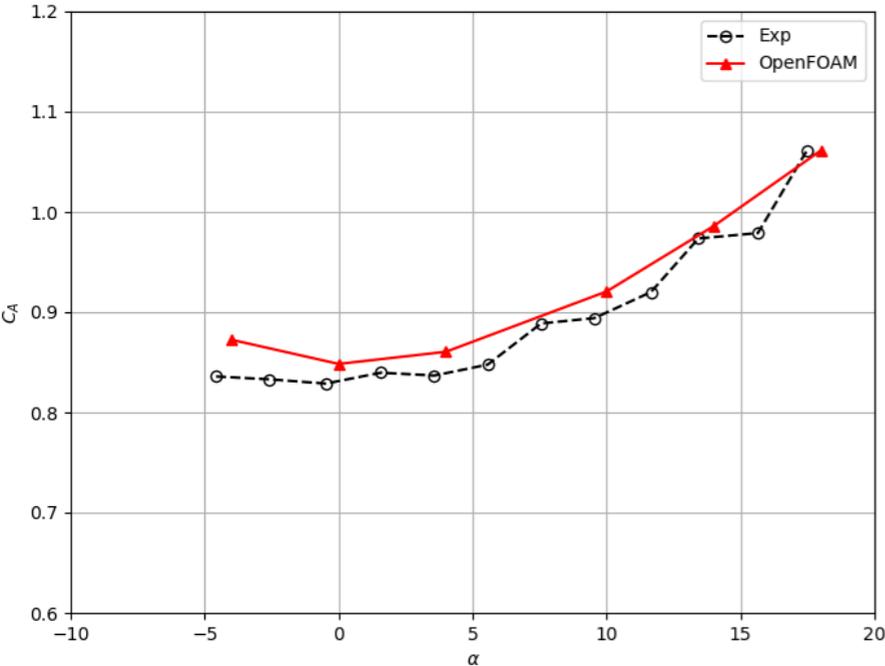
- ✓ Number of volume mesh : 25.5 million



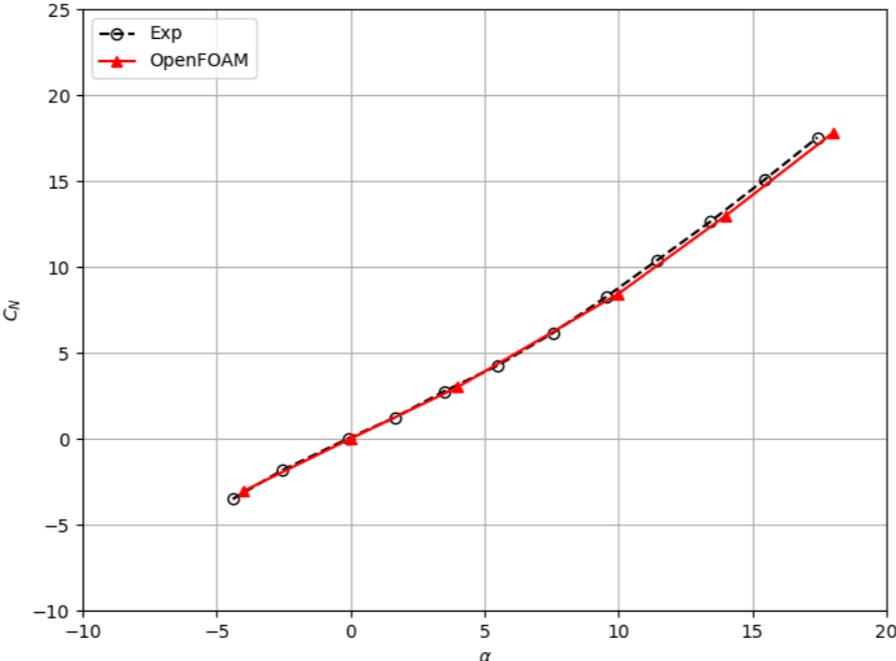
# Benchmark Test

## ○ Case 2 (NASA TP 2157)

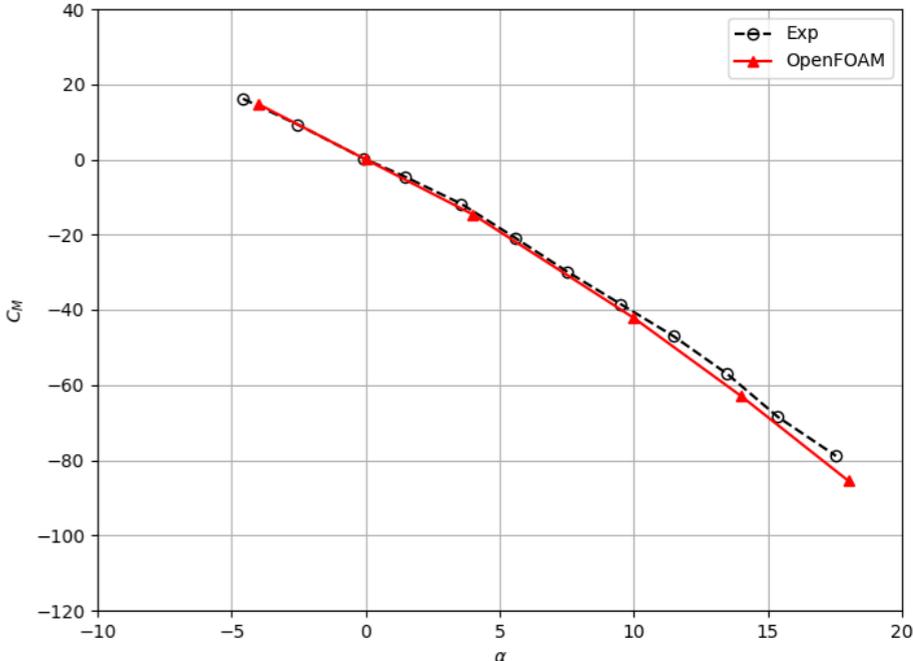
- Overpredict axial force but matches well in the overall trend
- Normal force and pitching moment are in very good agreement



Axial Force Coefficient



Normal Force Coefficient

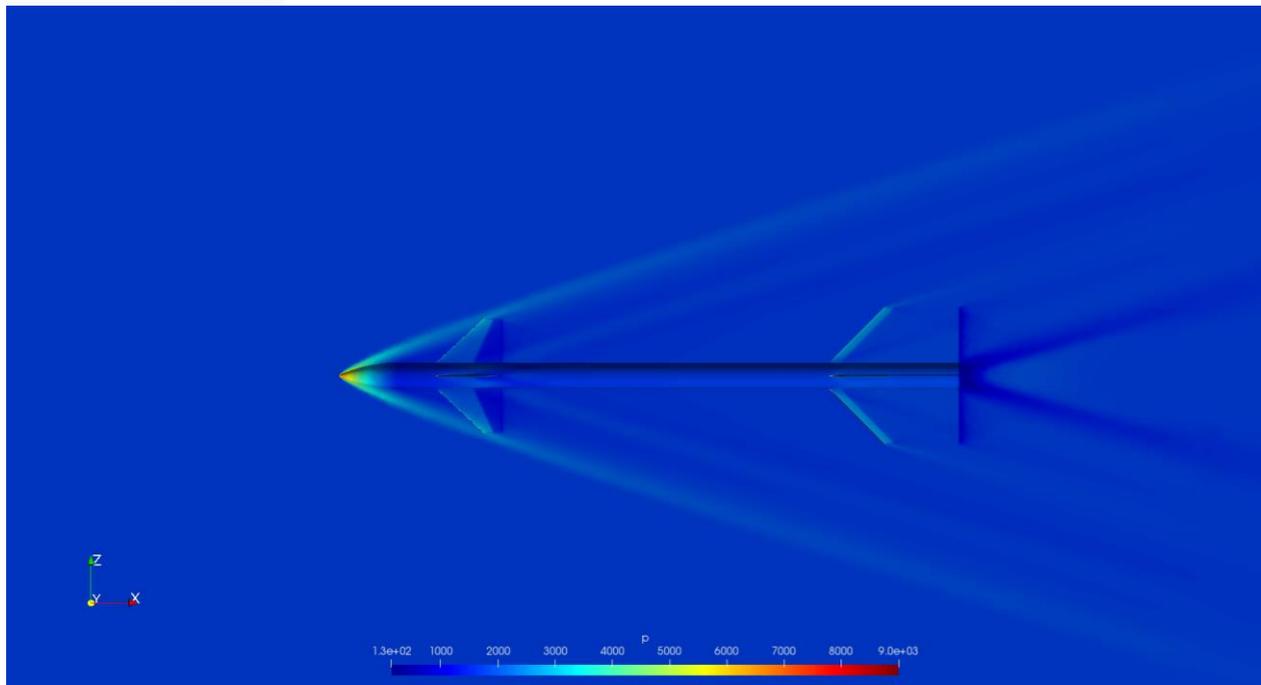


Pitching Moment Coefficient

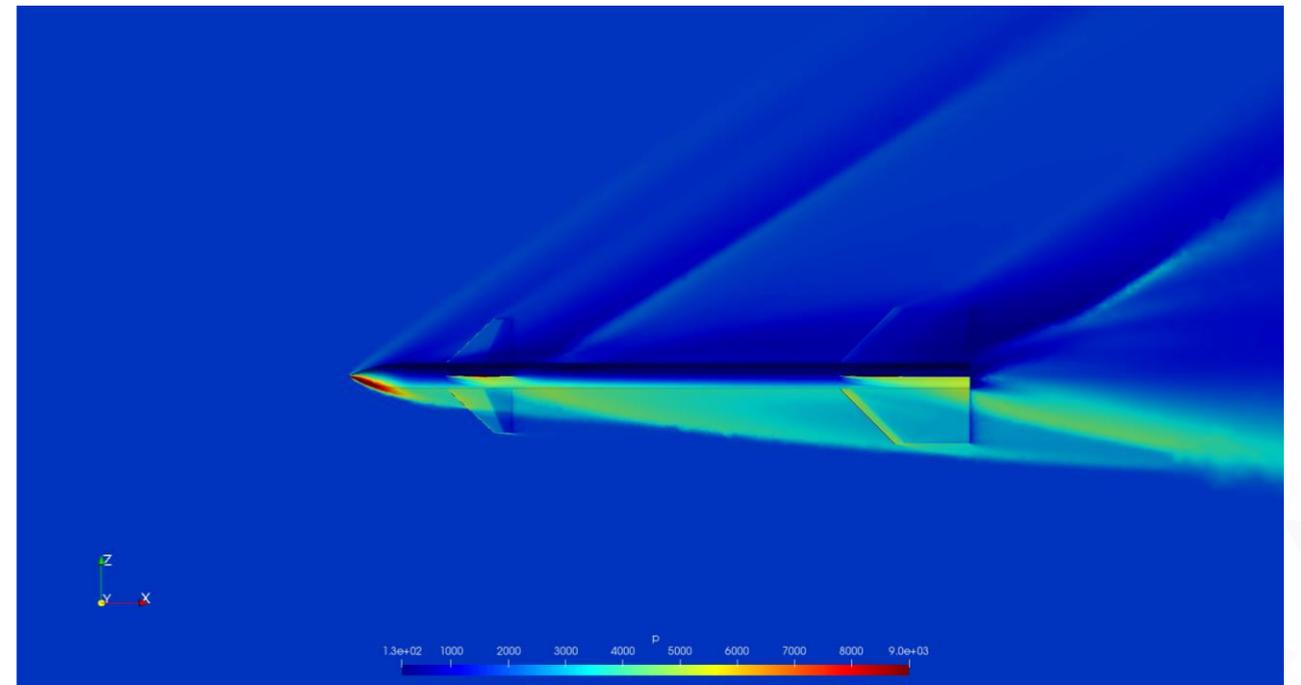
# Benchmark Test

- **Case 2 (NASA TP 2157)**

- Shock wave and wake flow are captured clearly by the use of the refinement regions



AoA = 0°



AoA = 32°

# Benchmark Test

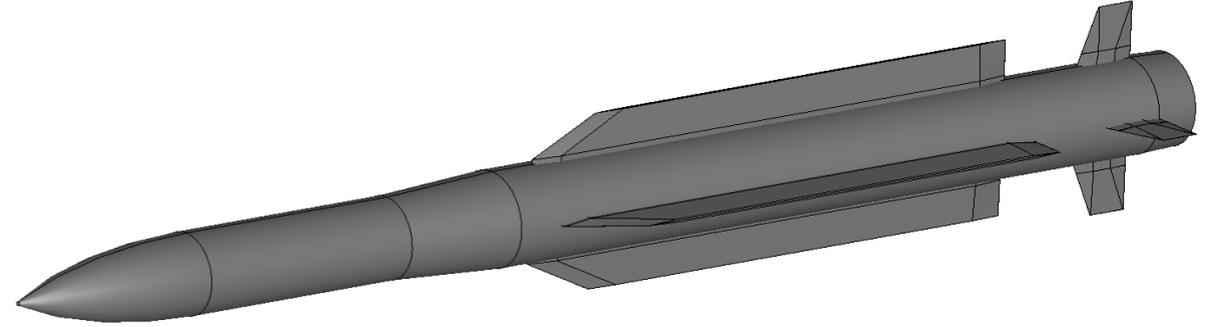
## ○ Case 3 (NASA TM 2005)

### • Geometry

- ✓ Body :  $(X, R)$  coordinate
- ✓ Finset : + Configuration,  $\delta_p = 10^\circ$

### • Flow Condition

- ✓ Mach Number : 2.36
- ✓ Reynolds number (per foot) :  $1.5 \times 10^6$
- ✓ Angle of attack ( $^\circ$ ) : -1.2, -0.18, 0.85, 1.79, 3.86, 5.86, 7.84, 9.85, 13.84, 16.85, 19.87

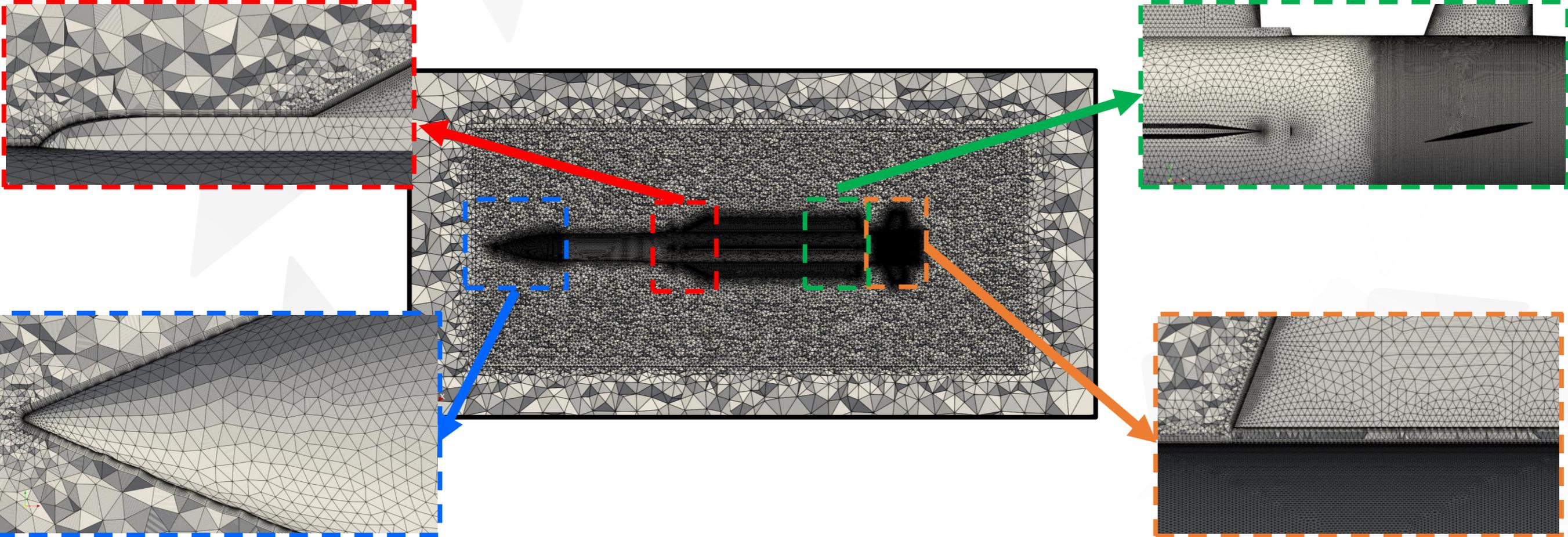


# Benchmark Test

- **Case 3 (NASA TM 2005)**

- Mesh

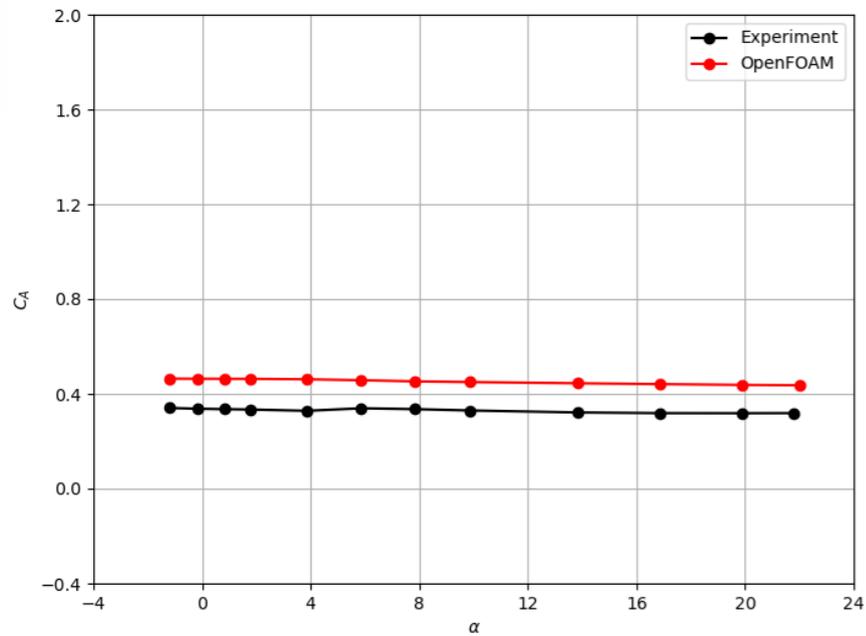
- ✓ Number of volume mesh : 28.2 million



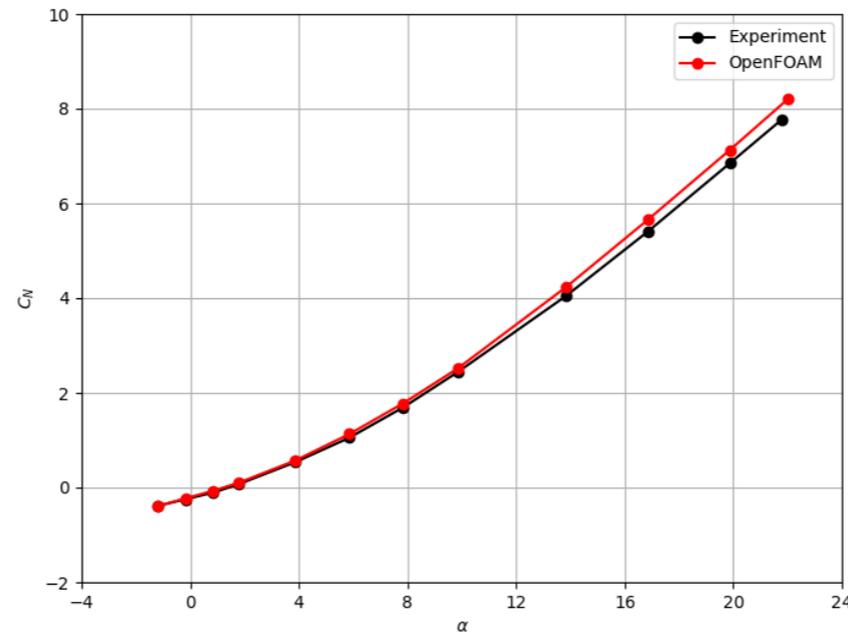
# Benchmark Test

## ○ Case 3 (NASA TM 2005)

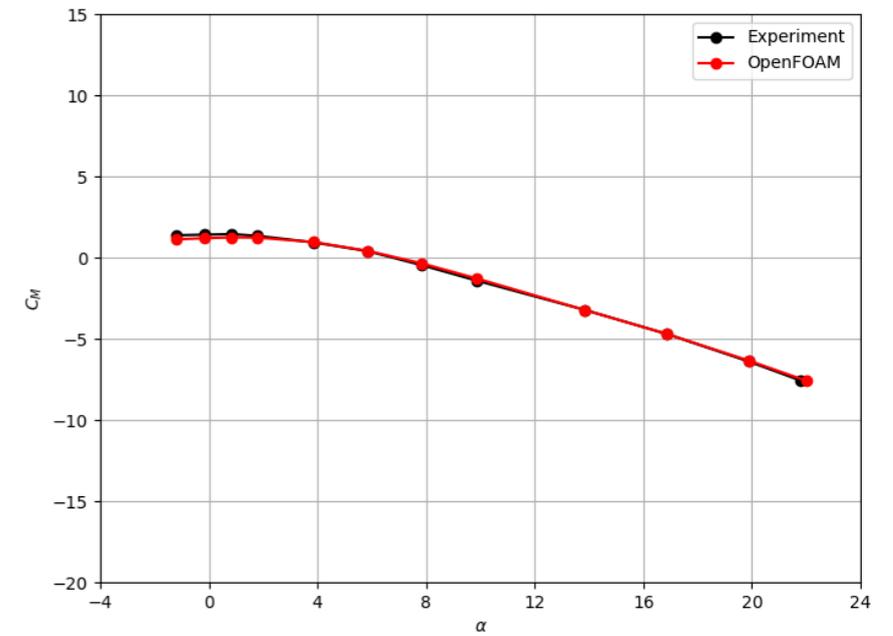
- Overpredict axial force compared to the experimental
- Normal force and pitching moment are in very good agreement



Axial Force Coefficient



Normal Force Coefficient

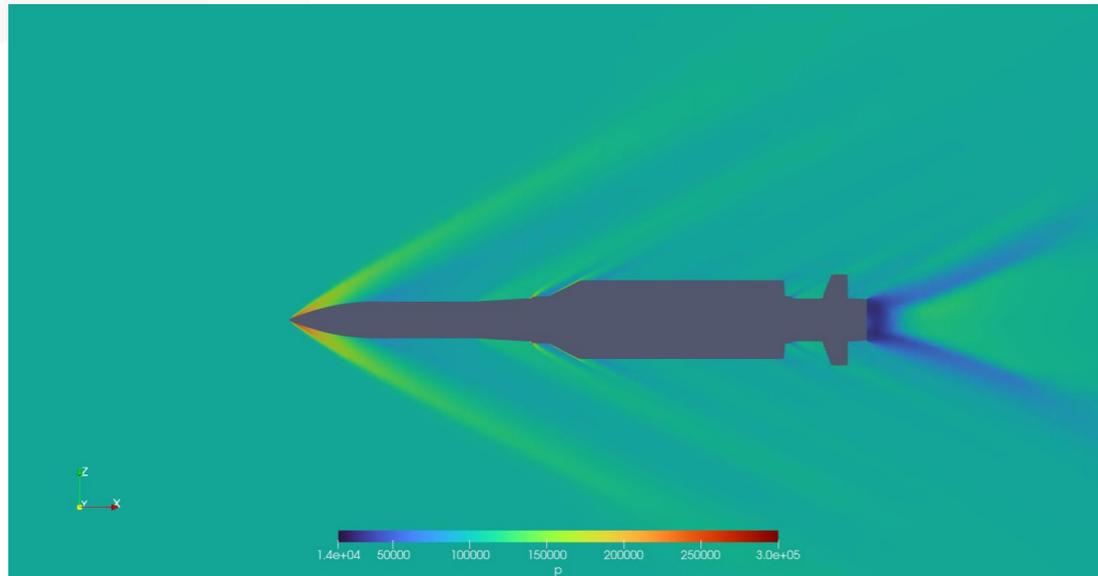
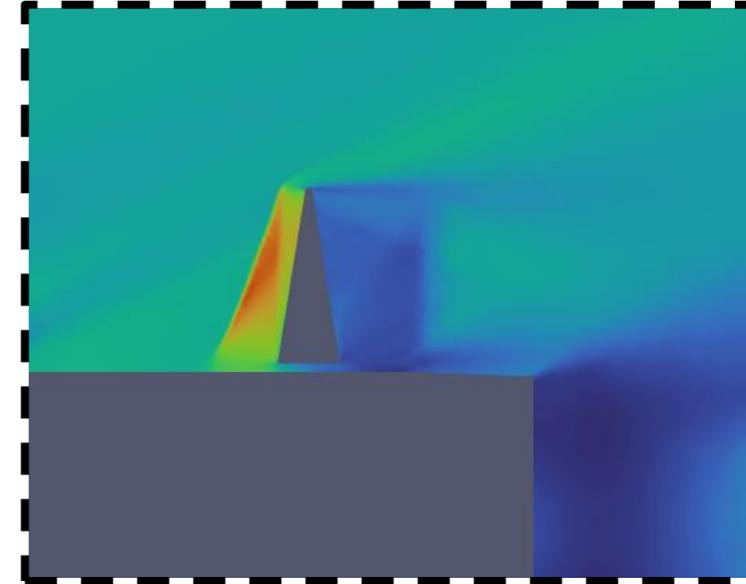


Pitching Moment Coefficient

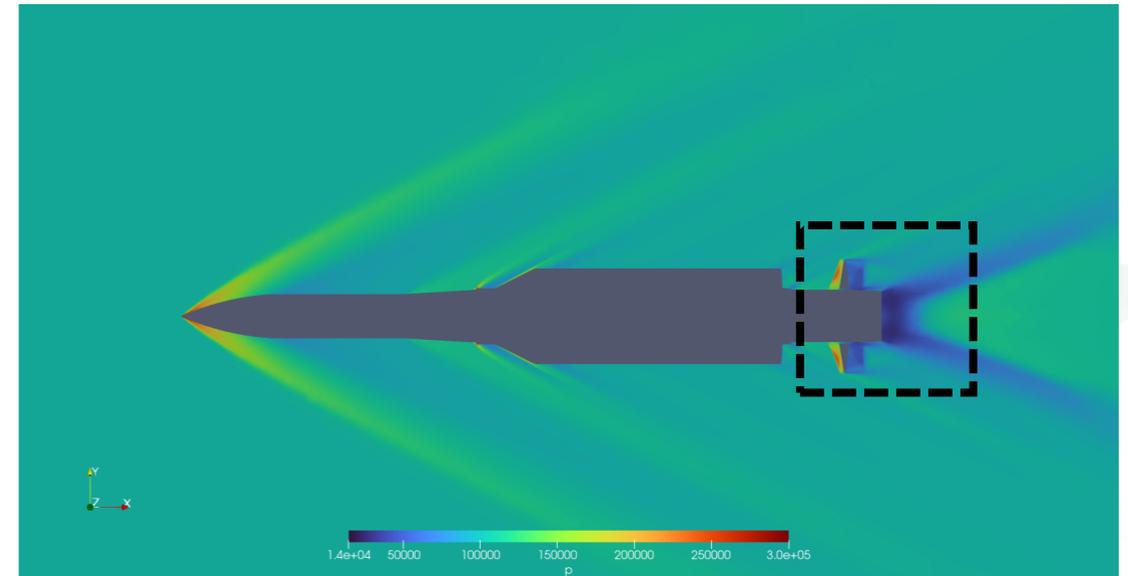
# Benchmark Test

- **Case 3 (NASA TM 2005)**

- Shock wave and wake flow are captured clearly by the use of the refinement regions
- Flow field around gap is shown physically



AoA = 0.85° (X – Z Plane)



AoA = 0.85° (X – Y Plane)

# Conclusion

## ○ Automated Aerodynamic Process

- Developed to be **applicable for arbitrary missile configuration**
- Composed of geometry, mesh, flow analysis and post-processing modules
- Use open-source software in all modules
  - ✓ OpenCASCADE, Salome, OpenFOAM, ParaView
- **Minimize user intervention** using defined parameters
- Perform benchmark test with 3 different missile configurations

**Thank you for attention**