$$A = [a_{ij}] = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} A^2 X B A = A B \\ A^{-2} A^2 X B A = A^{-2} A B \\ X B A = A^{-1} B \\ X B A A^{-1} = A^{-1} B A^{-1} \\ X B B A^{-1} = A^{-1} B A^{-1} \\ X B B^{-1} = A^{-1} B A^{-1} B^{-1} \\ X B B^{-1} = A^{-1} B A^{-1} B^{-1} \\ X B B^{-1} = A^{-1} B A^{-1} B^{-1} \end{bmatrix}$$

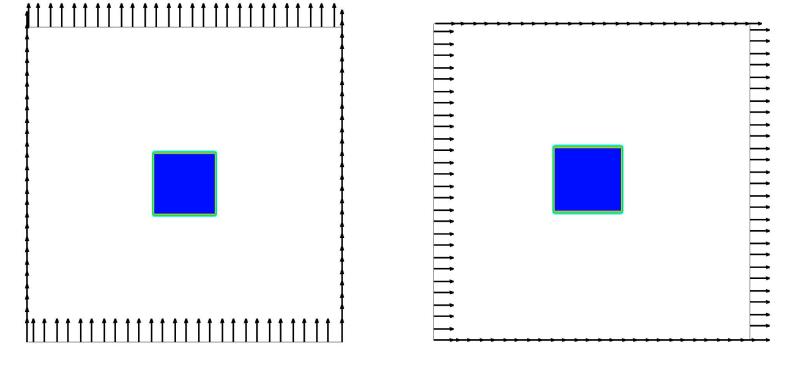
Stabilization of Gauss-Seidel Smoother

NAOFE, Dong-A university

Yeoun Joo KIM

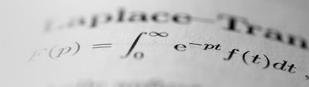
Motivation

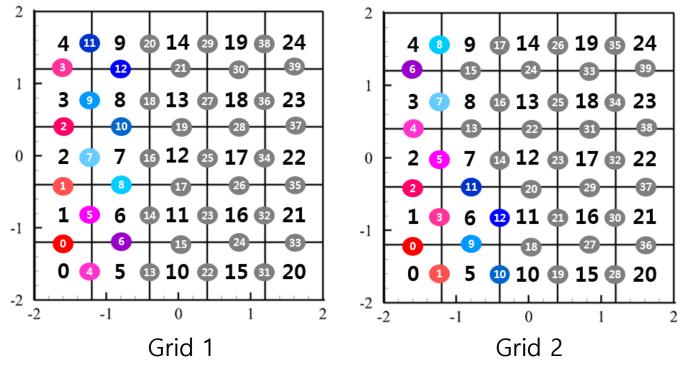
 $f(p) = \int_0^\infty e^{-pt} f(t) dt$



▶ x방향으로 흐르지 못하는 이유는?

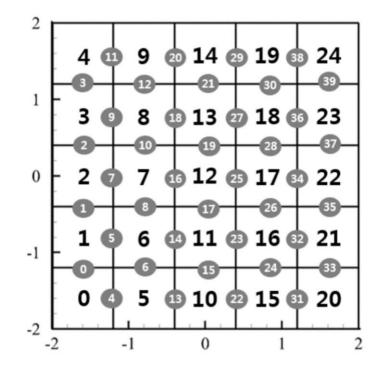
Cases of Face-Ordering





Different ordering of face index in two grid systems

 $f(p) = \int_0^\infty e^{-pt} f(t) dt$



for (label celli=0; celli<nCells; celli++)
{
 // Start and end of this row
 fStart = fEnd;
 fEnd = ownStartPtr[celli + 1];
 // Get the accumulated neighbour side
 psii = bPrimePtr[celli];
 // Accumulate the owner product side
 for (label facei=fStart; facei<fEnd; facei++)
 {
 psii -= upperPtr[facei]*psiPtr[uPtr[facei]];
 }
}</pre>

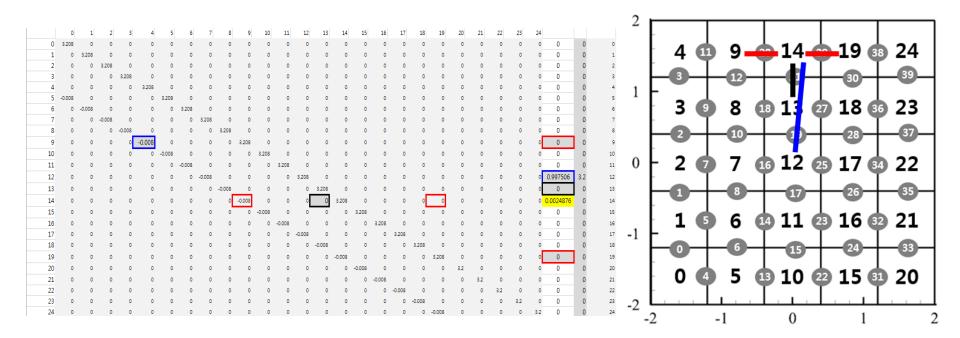
$$\varphi_{i,j} = l_{i-1}\varphi_{i-1,j} + u_{i+1}\varphi_{i+1,j} \quad \text{missed}$$

$$+ l_{j-1}\varphi_{i,j-1} + u_{j+1}\varphi_{i,j+1}$$

$$+ d_{k,l}\varphi_{k,l} \quad \text{misplaced}$$

$$\begin{cases} k \neq i - 1, i + 1 \\ l \neq j - 1, j + 1 \end{cases}$$

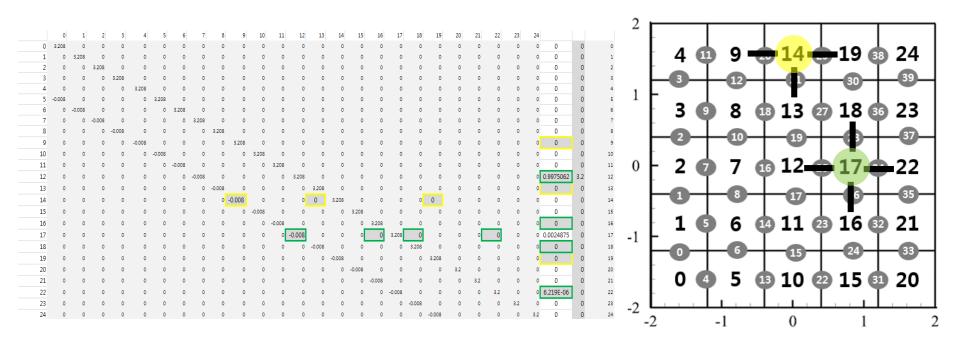
 $f(p) = \int_0^\infty e^{-pt} f(t) dt$



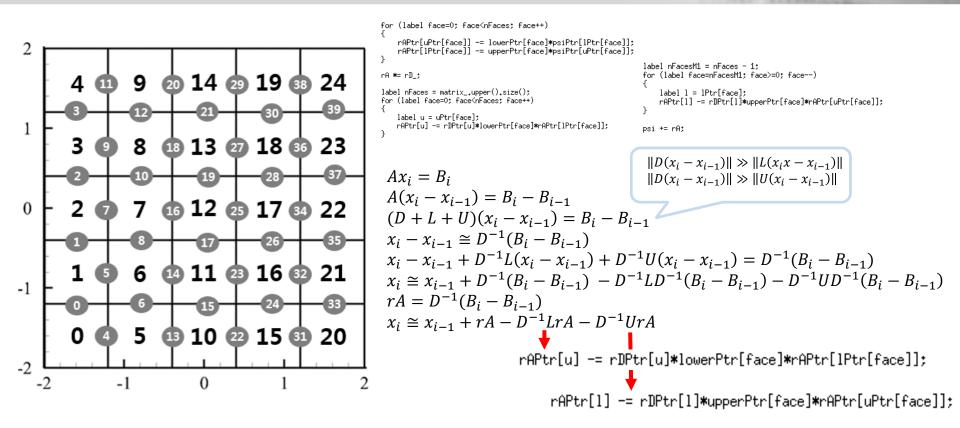
 $f(p) = \int_0^\infty e^{-pt} f(t) dt$

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13 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
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 $f(p) = \int_0^\infty e^{-pt} f(t) dt$



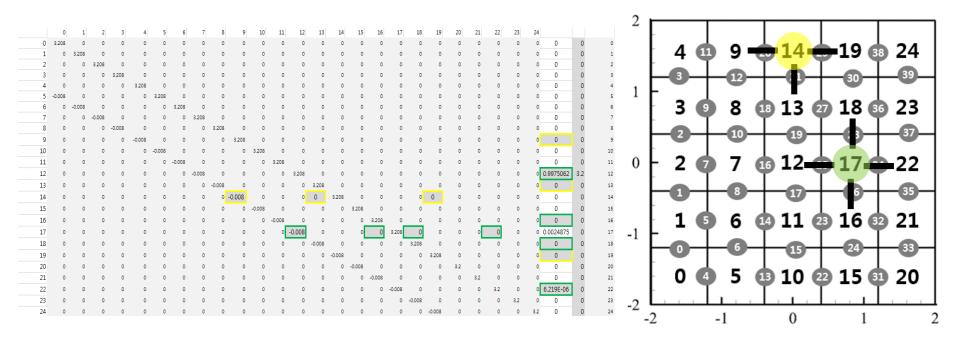
DILU Smoother : Grid 1



 $f(p) = \int_0^\infty e^{-pt} f(t) dt$

DILU Smoother : Grid 1

 $f(p) = \int_0^\infty e^{-pt} f(t) dt$



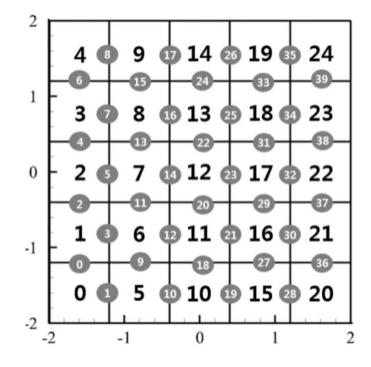
Other Smoothers

 $f(p) = \int_0^\infty e^{-pt} f(t) dt$

DILUGaussSeidel solver nonBlockingGaussSeidel solver diluSmoother_.smooth(psi, source, cmpt, nSweeps); for (label celli=0; celli<blockStart; celli++)</pre> for (label celli=blockStart; celli < nCells; celli++)</pre> qsSmoother_.smooth(psi, source, cmpt, nSweeps); // Start and end of this row // Start and end of this row fStart = fEnd:fStart = fEnd: fEnd = ownStartPtr[celli + 1]: fEnd = ownStartPtr[celli + 1]: // Get the accumulated neighbour side // Get the accumulated neighbour side symGaussSeidel solver curPsi = bPrimePtr[celli]; curPsi = bPrimePtr[celli]; // Accumulate the owner product side // Accumulate the owner product side fStart = ownStartPtr[nCells]; for (label curFace=fStart; curFace<fEnd; curFace++)</pre> for (label curFace=fStart; curFace<fEnd; curFace++)</pre> for (label celli=0; celli<nCells; celli++)</pre> for (label celli=nCells-1; celli>=0; celli--) curPsi -= upperPtr[curFace]*psiPtr[uPtr[curFace]]: curPsi -= upperPtr[curFace]*psiPtr[uPtr[curFace]]: // Start and end of this row fStart = fEndt// Start and end of this row fEnd = ownStartPtr[celli + 1]; fEnd = fStart: // Finish current psi // Finish current psi fStart = ownStartPtr[celli]; // Get the accumulated neighbour side curPsi /= diagPtr[celli]; curPsi /= diagPtr[celli]; psii = bPrimePtr[celli]: // Get the accumulated neighbour side psii = bPrimePtr[celli]: // Distribute the neighbour side using current psi // Distribute the neighbour side using current psi for (label curFace=fStart; curFace<fEnd; curFace++)</pre> // Accumulate the owner product side for (label curFace=fStart; curFace<fEnd; curFace++)</pre> // Accumulate the owner product side for (label facei=fStart: facei<fEnd: facei++)</pre> bPrimePtr[uPtr[curFace]] -= lowerPtr[curFace]*curPsi; for (label facei=fStart; facei<fEnd; facei++)</pre> bPrimePtr[uPtr[curFace]] -= lowerPtr[curFace]*curPsi: psii -= upperPtr[facei]*psiPtr[uPtr[facei]]; psii -= upperPtr[facei]*psiPtr[uPtr[facei]]; psiPtr[celli] = curPsi; psiPtr[celli] = curPsi: // Finish current psi // Finish psi for this cell psii /= diagPtr[celli]; psii /= diagPtr[celli]; // Distribute the neighbour side using current psi // Distribute the neighbour side using psi for this cell for (label facei=fStart: facei<fEnd: facei++)</pre> for (label facei=fStart; facei<fEnd; facei++)</pre> bPrimePtr[uPtr[facei]] -= lowerPtr[facei]*psii: bPrimePtr[uPtr[facei]] -= lowerPtr[facei]*psii; psiPtr[celli] = psii; psiPtr[celli] = psii; 3 fStart = ownStartPtr[nCells];

Based on GaussSeidel solver

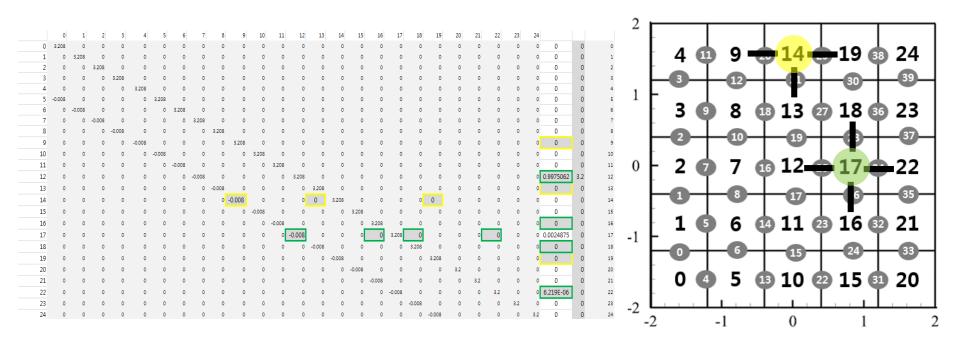
 $f(p) = \int_0^\infty e^{-pt} f(t) dt$



for (label celli=0; celli<nCells; celli++)
{
 // Start and end of this row
 fStart = fEnd;
 fEnd = ownStartPtr[celli + 1];
 // Get the accumulated neighbour side
 psii = bPrimePtr[celli];
 // Accumulate the owner product side
 for (label facei=fStart; facei<fEnd; facei++)
 {
 psii -= upperPtr[facei]*psiPtr[uPtr[facei]];
 }
</pre>

 $\varphi_{i,j} = l_{i-1}\varphi_{i-1,j} + u_{i+1}\varphi_{i+1,j}$ $+ l_{j-1}\varphi_{i,j-1} + u_{j+1}\varphi_{i,j+1}$

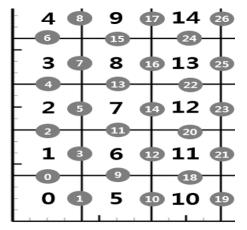
 $f(p) = \int_0^\infty e^{-pt} f(t) dt$



Code Analysis of GS

```
scalar psii;
label fStart:
label fEnd = ownStartPtr[0]: _____ start owner face at each cell
for (label celli=0; celli<nCells; celli++)</pre>
   // Start and end of this row
   fEnd = ownStartPtr[celli + 1]; -----> start owner face at next cell
   // Get the accumulated neighbour side
   psii = bPrimePtr[celli];
   // Accumulate the owner product side
   for (label facei=fStart; facei<fEnd; facei++)</pre>
       psii -= upperPtr[facei]*psiPtr[uPtr[facei]];
   }
                                 \rightarrow psi at cell of owner faces
   // Finish psi for this cell
   psii /= diagPtr[celli];
   // Distribute the neighbour side using psi for this cell
   for (label facei=fStart; facei<fEnd; facei++)</pre>
       bPrimePtr[uPtr[facei]] -= lowerPtr[facei]*psii;
   }
                           → psi at cell of neighbour faces
   psiPtr[celli] = psii;
3
```

 $f(p) = \int_0^\infty e^{-pt} f(t) dt$

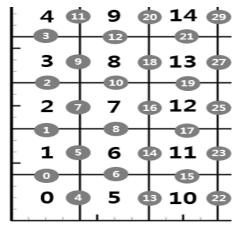


	faceIndex	
cellIndex	fStart/ownStart	fEnd
0	0	2
1	2	4
2	4	6
3	6	8
4	8	9
5	9	11
6	11	13

Code Analysis of GS

```
scalar psii;
label fStart:
label fEnd = ownStartPtr[0]: _____ start owner face at each cell
for (label celli=0; celli<nCells; celli++)</pre>
   // Start and end of this row
   fEnd = ownStartPtr[celli + 1]; -----> start owner face at next cell
   // Get the accumulated neighbour side
   psii = bPrimePtr[celli];
   // Accumulate the owner product side
   for (label facei=fStart; facei<fEnd; facei++)</pre>
       psii -= upperPtr[facei]*psiPtr[uPtr[facei]];
   }
                                 \rightarrow psi at cell of owner faces
   // Finish psi for this cell
   psii /= diagPtr[celli];
   // Distribute the neighbour side using psi for this cell
   for (label facei=fStart; facei<fEnd; facei++)</pre>
       bPrimePtr[uPtr[facei]] -= lowerPtr[facei]*psii;
   }
                           → psi at cell of neighbour faces
   psiPtr[celli] = psii;
3
```

 $f(p) = \int_0^\infty e^{-pt} f(t) dt$

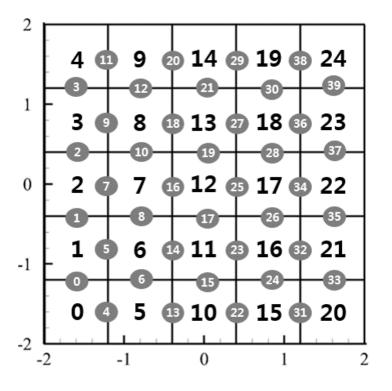


	faceIndex	
cellIndex	fStart/ownStart	fEnd
0	0	1
1	1	2
2	2	3
3	3	6
4	6	6
5	6	8
6	8	10

Stabilization of GS

3

 $f(p) = \int_0^\infty e^{-pt} f(t) dt$



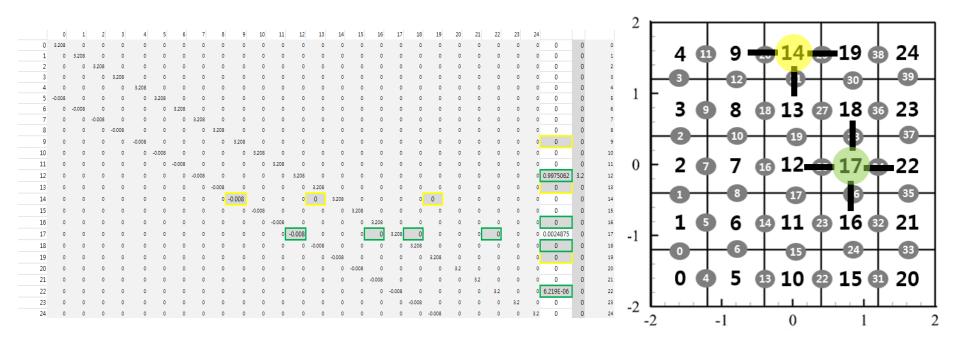
for(label celli=0;celli<nCells;celli++) psiPtr[celli] = bPrimePtr[celli]/diagPtr[celli];
for(label facei=0;facei<nFaces;facei++)</pre>

psiPtr[lPtr[facei]] -= upperPtr[facei]*psiPtr[uPtr[facei]]/diagPtr[lPtr[facei]]; psiPtr[uPtr[facei]] -= lowerPtr[facei]*psiPtr[lPtr[facei]]/diagPtr[uPtr[facei]];

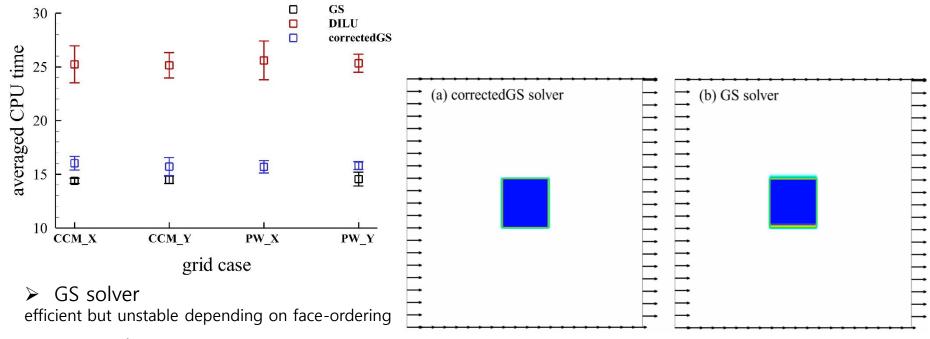
$$\varphi_{i,j} = (l_{i-1}\varphi_{i-1,j} + u_{i+1}\varphi_{i+1,j} + l_{j-1}\varphi_{i,j-1} + u_{j+1}\varphi_{i,j+1})/D_i$$

Stabilization of GS

 $p(p) = \int_0^\infty e^{-pt} f(t) dt$



Performance of correctedGS / ~ e-ref(t) dt



DILU solver stable but inefficient

correctedGS solver efficient and stable